

Tutorial on SAT

Armin Biere



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Dress Code Tutorial Speaker as SAT Problem

- propositional logic:

- variables **tie** **shirt**
- negation \neg (not)
- disjunction \vee (or)
- conjunction \wedge (and)

- clauses (conditions / constraints)

1. clearly one should not wear a **tie** without a **shirt** $\neg\text{tie} \vee \text{shirt}$

2. not wearing a **tie** nor a **shirt** is impolite $\text{tie} \vee \text{shirt}$

3. wearing a **tie** and a **shirt** is overkill $\neg(\text{tie} \wedge \text{shirt}) \equiv \neg\text{tie} \vee \neg\text{shirt}$

- Is this formula in conjunctive normal form (CNF) **satisfiable**?

$$(\neg\text{tie} \vee \text{shirt}) \wedge (\text{tie} \vee \text{shirt}) \wedge (\neg\text{tie} \vee \neg\text{shirt})$$









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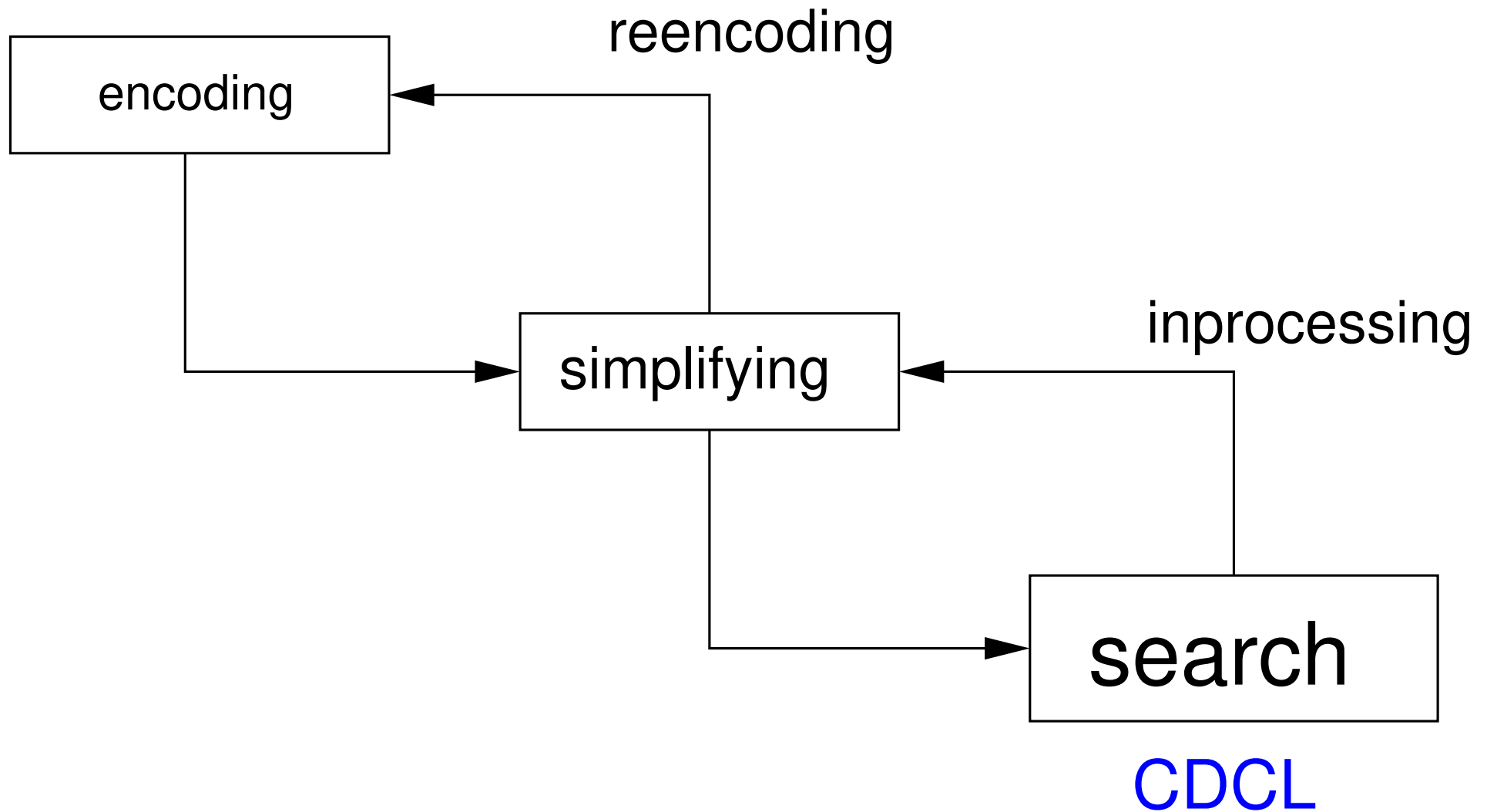
* * *

Wow — Section 7.2.2.2 has turned out to be the longest section, by far, in *The Art of Computer Programming*. The SAT problem is evidently a “killer app,” because it is key to the solution of so many other problems. Consequently I can only hope that my lengthy treatment does not also kill off my faithful readers! As I wrote this material, one topic always seemed to flow naturally into another, so there was no neat way to break this section up into separate subsections. (And anyway the format of *TAOCP* doesn't allow for a Section 7.2.2.2.1.)

I've tried to ameliorate the reader's navigation problem by adding subheadings at the top of each right-hand page. Furthermore, as in other sections, the exercises appear in an order that roughly parallels the order in which corresponding topics are taken up in the text. Numerous cross-references are provided

Biere
Bryant
Buss
Eén
Gent
Heule
Hoos
Janson
Jeavons
Kroening
Kullmann
Lauria
Pegden
Shortz
Sinz
Sörensson
Wermuth
Williams
Internet
MPR
Internet

What is Practical SAT Solving?



Equivalence Checking If-Then-Else Chains

original C code

```
if(!a && !b) h();  
else if(!a) g();  
else f();
```



```
if(!a) {  
    if(!b) h();  
    else g();  
} else f();
```

⇒

optimized C code

```
if(a) f();  
else if(b) g();  
else h();
```



```
if(a) f();  
else {  
    if(!b) h();  
    else g(); }  
}
```

How to check that these two versions are equivalent?

Compilation

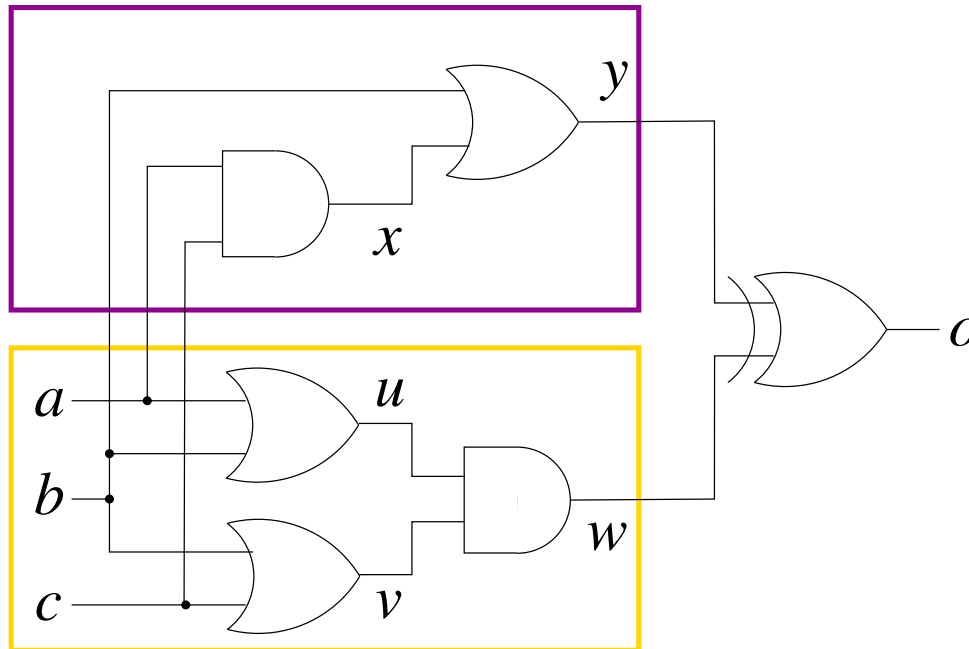
$$\begin{aligned} \textit{original} &\equiv \textbf{if } \neg a \wedge \neg b \textbf{ then } h \textbf{ else if } \neg a \textbf{ then } g \textbf{ else } f \\ &\equiv (\neg a \wedge \neg b) \wedge h \vee \neg(\neg a \wedge \neg b) \wedge \textbf{if } \neg a \textbf{ then } g \textbf{ else } f \\ &\equiv (\neg a \wedge \neg b) \wedge h \vee \neg(\neg a \wedge \neg b) \wedge (\neg a \wedge g \vee a \wedge f) \end{aligned}$$

$$\begin{aligned} \textit{optimized} &\equiv \textbf{if } a \textbf{ then } f \textbf{ else if } b \textbf{ then } g \textbf{ else } h \\ &\equiv a \wedge f \vee \neg a \wedge \textbf{if } b \textbf{ then } g \textbf{ else } h \\ &\equiv a \wedge f \vee \neg a \wedge (b \wedge g \vee \neg b \wedge h) \end{aligned}$$

$$(\neg a \wedge \neg b) \wedge h \vee \neg(\neg a \wedge \neg b) \wedge (\neg a \wedge g \vee a \wedge f) \not\equiv a \wedge f \vee \neg a \wedge (b \wedge g \vee \neg b \wedge h)$$

satisfying assignment gives counter-example to equivalence

Tseitin Transformation: Circuit to CNF



$$\begin{array}{l} o \wedge \\ (x \leftrightarrow a \wedge c) \wedge \\ (y \leftrightarrow b \vee x) \wedge \\ (u \leftrightarrow a \vee b) \wedge \\ (v \leftrightarrow b \vee c) \wedge \\ (w \leftrightarrow u \wedge v) \wedge \\ (o \leftrightarrow y \oplus w) \end{array}$$

$$o \wedge (x \rightarrow a) \wedge (x \rightarrow c) \wedge (x \leftarrow a \wedge c) \wedge \dots$$

$$o \wedge (\bar{x} \vee a) \wedge (\bar{x} \vee c) \wedge (x \vee \bar{a} \vee \bar{c}) \wedge \dots$$

Tseitin Transformation: Gate Constraints

Negation: $x \leftrightarrow \bar{y} \Leftrightarrow (x \rightarrow \bar{y}) \wedge (\bar{y} \rightarrow x)$
 $\Leftrightarrow (\bar{x} \vee \bar{y}) \wedge (y \vee x)$

Disjunction: $x \leftrightarrow (y \vee z) \Leftrightarrow (y \rightarrow x) \wedge (z \rightarrow x) \wedge (x \rightarrow (y \vee z))$
 $\Leftrightarrow (\bar{y} \vee x) \wedge (\bar{z} \vee x) \wedge (\bar{x} \vee y \vee z)$

Conjunction: $x \leftrightarrow (y \wedge z) \Leftrightarrow (x \rightarrow y) \wedge (x \rightarrow z) \wedge ((y \wedge z) \rightarrow x)$
 $\Leftrightarrow (\bar{x} \vee y) \wedge (\bar{x} \vee z) \wedge \overline{((y \wedge z) \vee x)}$
 $\Leftrightarrow (\bar{x} \vee y) \wedge (\bar{x} \vee z) \wedge (\bar{y} \vee \bar{z} \vee x)$

Equivalence: $x \leftrightarrow (y \leftrightarrow z) \Leftrightarrow (x \rightarrow (y \leftrightarrow z)) \wedge ((y \leftrightarrow z) \rightarrow x)$
 $\Leftrightarrow (x \rightarrow ((y \rightarrow z) \wedge (z \rightarrow y))) \wedge ((y \leftrightarrow z) \rightarrow x)$
 $\Leftrightarrow (x \rightarrow (y \rightarrow z)) \wedge (x \rightarrow (z \rightarrow y)) \wedge ((y \leftrightarrow z) \rightarrow x)$
 $\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge ((y \leftrightarrow z) \rightarrow x)$
 $\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge (((y \wedge z) \vee (\bar{y} \wedge \bar{z})) \rightarrow x)$
 $\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge ((y \wedge z) \rightarrow x) \wedge ((\bar{y} \wedge \bar{z}) \rightarrow x)$
 $\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge (\bar{y} \vee \bar{z} \vee x) \wedge (y \vee z \vee x)$

Bit-Blasting of Bit-Vector Addition

addition of 4-bit numbers x, y with result s also 4-bit: $s = x + y$

$$[s_3, s_2, s_1, s_0]_4 = [x_3, x_2, x_1, x_0]_4 + [y_3, y_2, y_1, y_0]_4$$

$$[s_3, \cdot]_2 = \text{FullAdder}(x_3, y_3, c_2)$$

$$[s_2, c_2]_2 = \text{FullAdder}(x_2, y_2, c_1)$$

$$[s_1, c_1]_2 = \text{FullAdder}(x_1, y_1, c_0)$$

$$[s_0, c_0]_2 = \text{FullAdder}(x_0, y_0, \text{false})$$

where

$$[s, o]_2 = \text{FullAdder}(x, y, i) \quad \text{with}$$

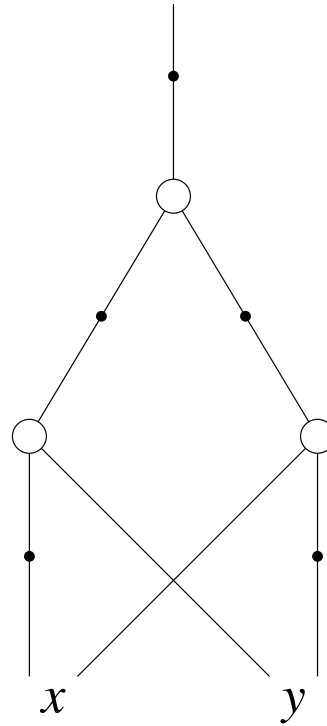
$$s = x \text{ xor } y \text{ xor } i$$

$$o = (x \wedge y) \vee (x \wedge i) \vee (y \wedge i) = ((x + y + i) \geq 2)$$

Intermediate Representations

- encoding directly into CNF is hard, so we use intermediate levels:
 1. application level
 2. bit-precise semantics world-level operations (bit-vectors)
 3. bit-level representations such as And-Inverter Graphs (AIGs)
 4. conjunctive normal form (CNF)
- encoding “logical” constraints is another story

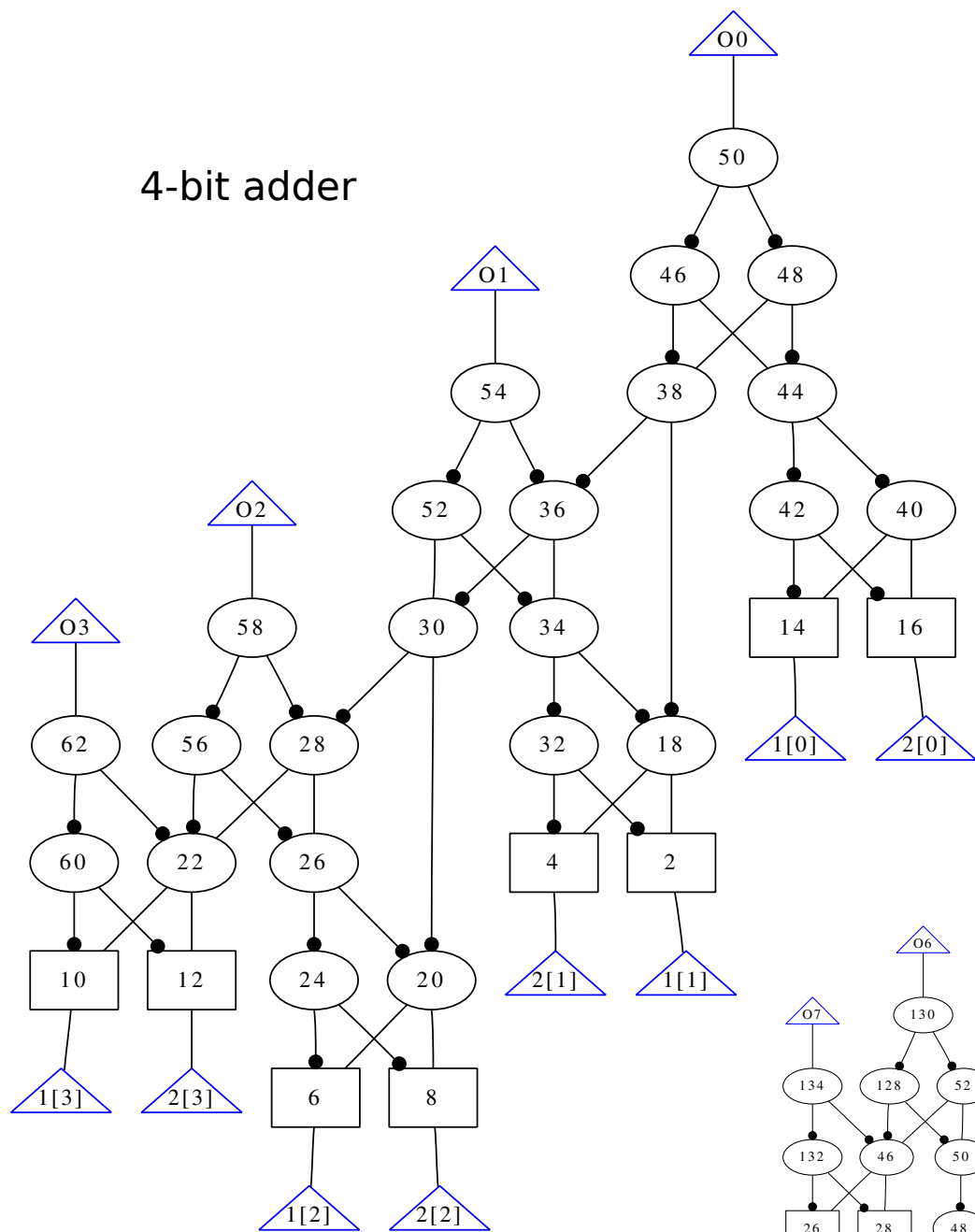
XOR as AIG



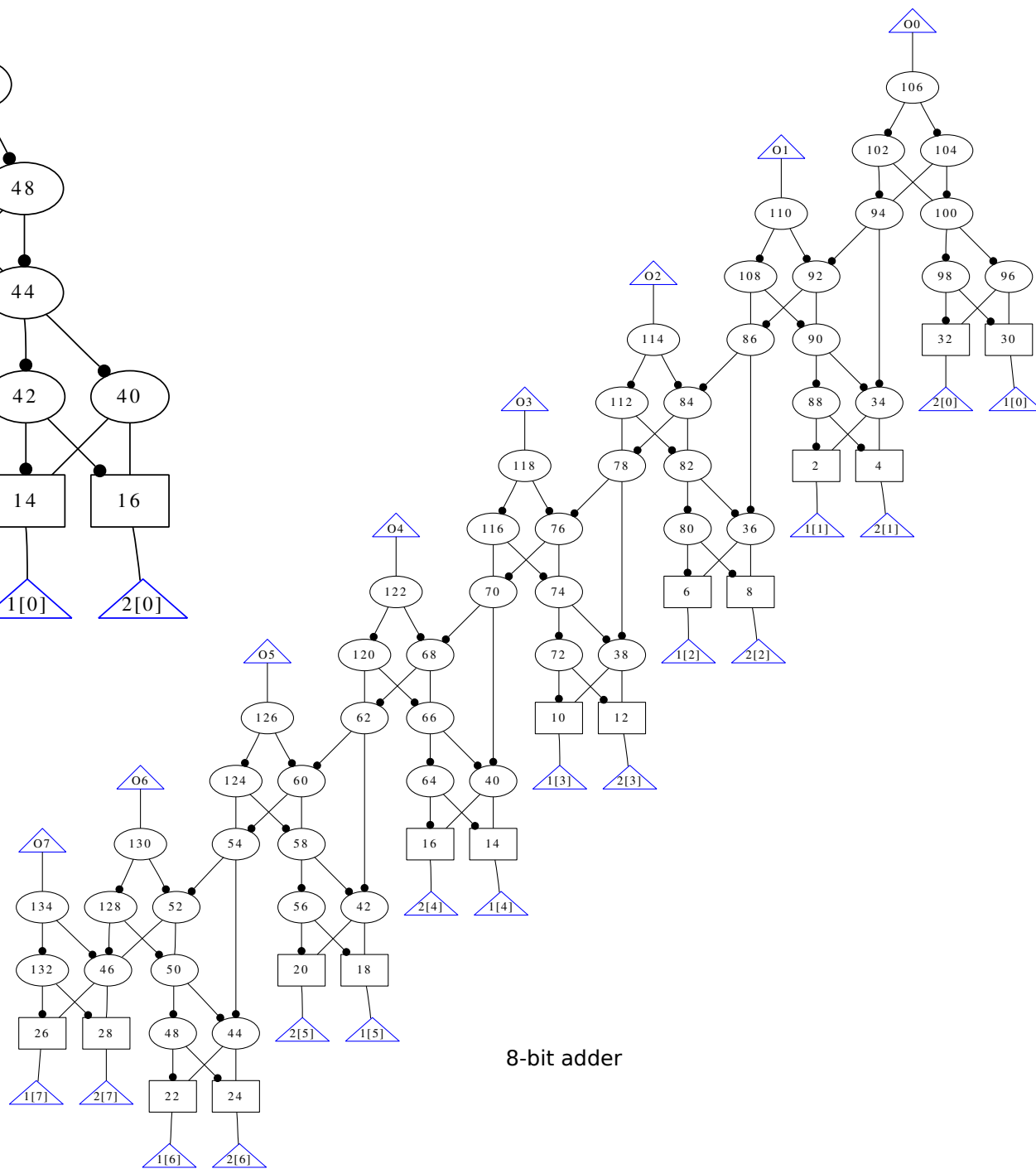
negation/sign are edge attributes
not part of node

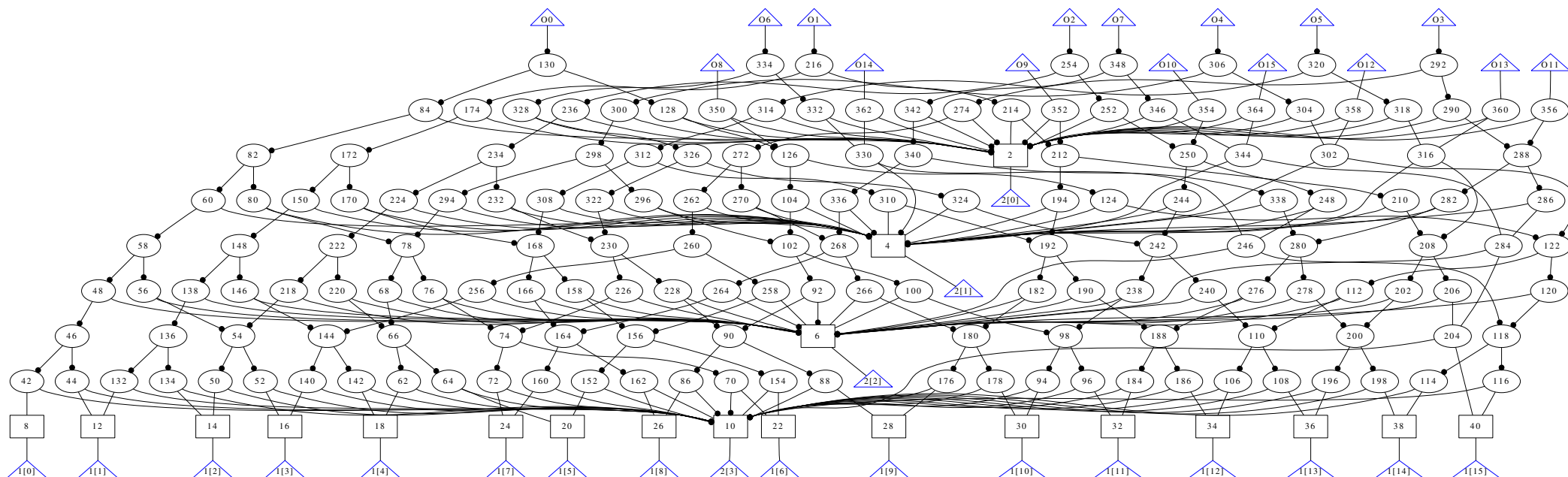
$$x \text{ xor } y \equiv (\bar{x} \wedge y) \vee (x \wedge \bar{y}) \equiv \overline{\overline{(\bar{x} \wedge y)} \wedge \overline{(x \wedge \bar{y})}}$$

4-bit adder

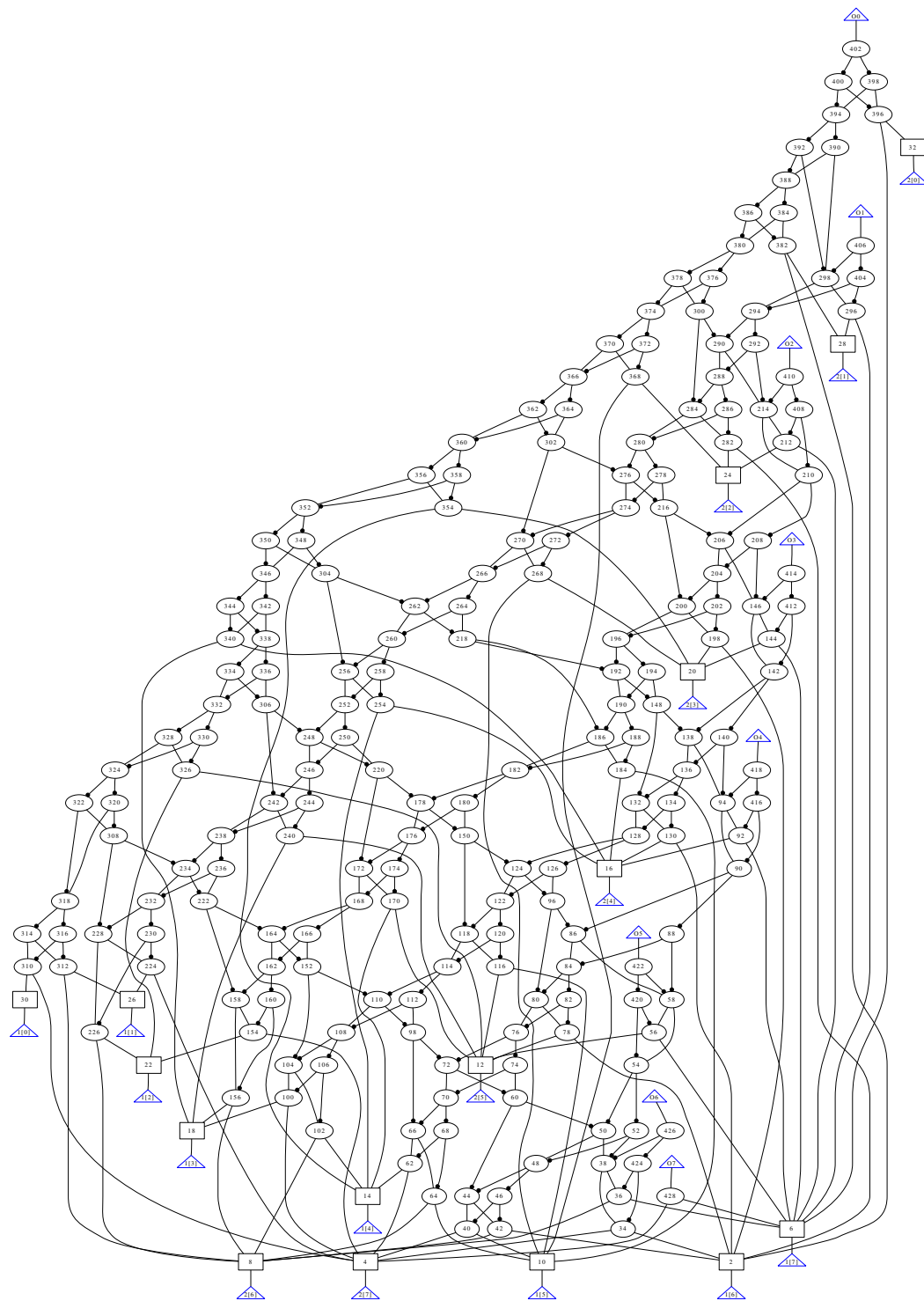


8-bit adder





bit-vector of length 16 shifted by bit-vector of length 4



Encoding Logical Constraints

- Tseitin's construction suitable for most kinds of “model constraints”
 - assuming simple operational semantics: encode an interpreter
 - small domains: one-hot encoding large domains: binary encoding
- harder to encode properties or additional constraints
 - temporal logic / fix-points
 - environment constraints
- example for fix-points / recursive equations: $x = (a \vee y), \quad y = (b \vee x)$
 - has unique least fix-point $x = y = (a \vee b)$
 - and unique largest fix-point $x = y = \text{true}$ but unfortunately ...
 - ... only largest fix-point can be (directly) encoded in SAT
otherwise need stable models / logical programming / ASP

Example of Logical Constraints: Cardinality Constraints

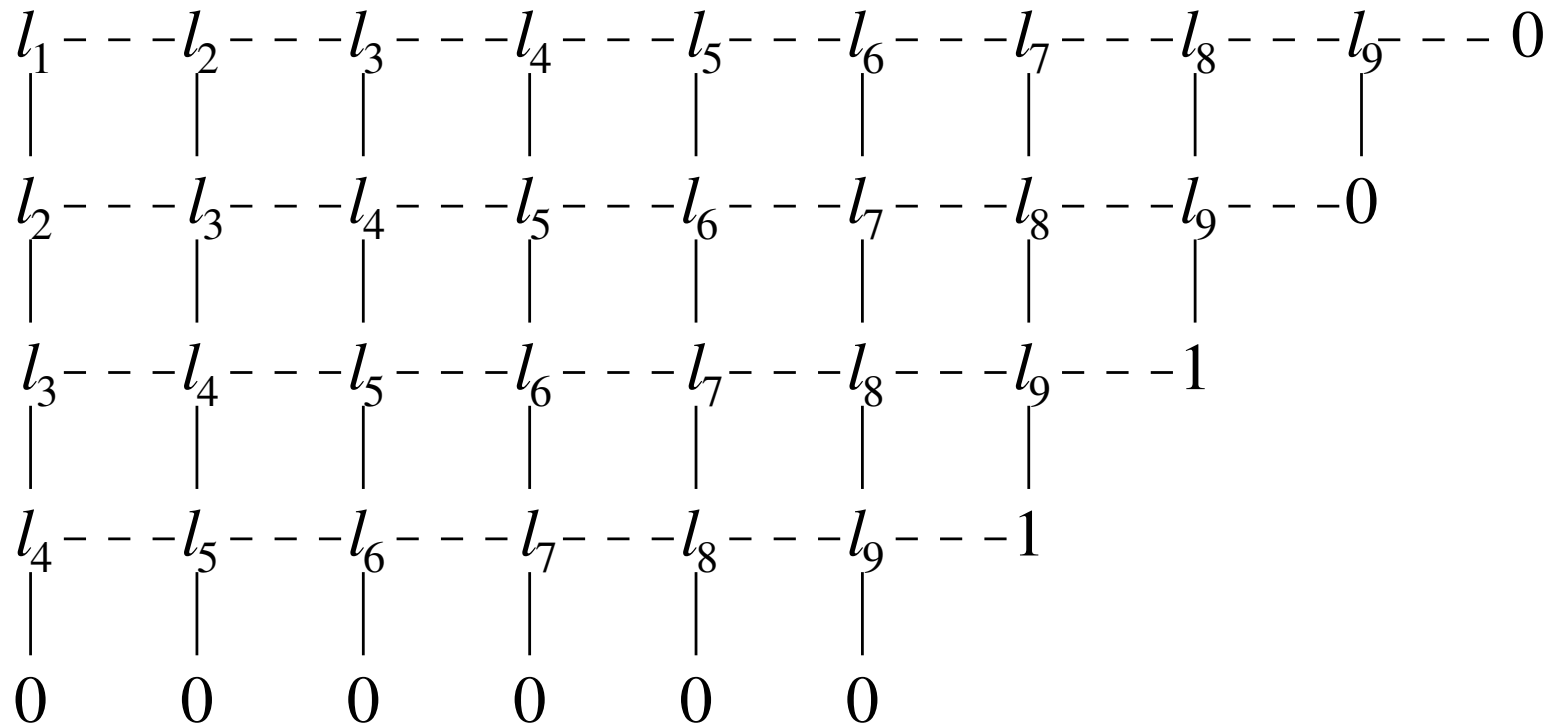
- given a set of literals $\{l_1, \dots, l_n\}$
 - constraint the number of literals assigned to *true*
 - $l_1 + \dots + l_n \geq k$ or $l_1 + \dots + l_n \leq k$ or $l_1 + \dots + l_n = k$
 - combined make up exactly all fully symmetric boolean functions
- multiple encodings of cardinality constraints
 - naïve encoding exponential: at-most-one quadratic, at-most-two cubic, etc.
 - quadratic $O(k \cdot n)$ encoding goes back to Shannon
 - linear $O(n)$ parallel counter encoding [Sinz'05]
- many variants even for at-most-one constraints
 - for an $O(n \cdot \log n)$ encoding see Prestwich's chapter in our Handbook of SAT
- Pseudo-Boolean constraints (PB) or 0/1 ILP constraints have many encodings too

$$2 \cdot \bar{a} + \bar{b} + c + \bar{d} + 2 \cdot e \geq 3$$

actually used to handle MaxSAT in SAT4J for configuration in Eclipse

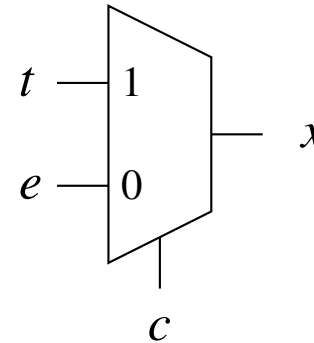
BDD-Based Encoding of Cardinality Constraints

$$2 \leq l_1 + \dots + l_9 \leq 3$$



If-Then-Else gates (MUX) with “then” edge downward, dashed “else” edge to the right

Tseitin Encoding of If-Then-Else Gate



$$\begin{aligned}x \leftrightarrow (c ? t : e) &\Leftrightarrow (x \rightarrow (c \rightarrow t)) \wedge (x \rightarrow (\bar{c} \rightarrow e)) \wedge (\bar{x} \rightarrow (c \rightarrow \bar{t})) \wedge (\bar{x} \rightarrow (\bar{c} \rightarrow \bar{e})) \\&\Leftrightarrow (\bar{x} \vee \bar{c} \vee t) \wedge (\bar{x} \vee c \vee e) \wedge (x \vee \bar{c} \vee \bar{t}) \wedge (x \vee c \vee \bar{e})\end{aligned}$$

minimal but not arc consistent:

- if t and e have the same value then x needs to have that too
- possible additional clauses

$$(\bar{t} \wedge \bar{e} \rightarrow \bar{x}) \equiv (t \vee e \vee \bar{x}) \qquad (t \wedge e \rightarrow x) \equiv (\bar{t} \vee \bar{e} \vee x)$$

- but can be learned or derived through preprocessing (ternary resolution)
keeping those clauses redundant is better in practice

DP / DPLL

- dates back to the 50'ies:

1st version DP is resolution based

⇒ preprocessing

2st version D(P)LL splits space for time

⇒

CDCL

- **ideas:**

- 1st version: eliminate the two cases of assigning a variable in space or

- 2nd version: case analysis in time, e.g. try $x = 0, 1$ in turn and recurse

- most successful SAT solvers are based on variant (CDCL) of the second version
works for very large instances

- recent (≤ 20 years) optimizations:

backjumping, learning, UIPs, dynamic splitting heuristics, fast data structures

(we will have a look at each of them)

DP Procedure

forever

if $F = \top$ **return** satisfiable

if $\perp \in F$ **return** unsatisfiable

pick remaining variable x

add all resolvents on x

remove all clauses with x and $\neg x$

\Rightarrow bounded variable elimination in SatELite preprocessor

Bounded Variable Elimination

[EénBiere-SAT'05]

Replace

$(\bar{x} \vee a)_1$	$(\bar{x} \vee c)_4$
$(\bar{x} \vee b)_2$	$(x \vee d)_5$
$(x \vee \bar{a} \vee \bar{b})_3$	

by

$(a \vee \bar{a} \vee \bar{b})_{13}$	$(a \vee d)_{15}$	$(c \vee d)_{45}$
$(b \vee \bar{a} \vee \bar{b})_{23}$	$(b \vee d)_{25}$	
$(c \vee \bar{a} \vee \bar{b})_{34}$		

- number of clauses not increasing
- strengthen and remove subsumed clauses too
- most important and most effective preproessing we have

Bounded Variable Addition

[MantheyHeuleBiere-HVC'12]

Replace

$(a \vee d)$	$(a \vee e)$
$(b \vee d)$	$(b \vee e)$
$(c \vee d)$	$(c \vee e)$

by

$(\bar{x} \vee a)$	$(\bar{x} \vee b)$	$(\bar{x} \vee c)$
$(x \vee d)$	$(x \vee e)$	

- number of clauses has to decrease strictly
- reencodes for instance naive at-most-one constraint encodings

D(P)LL Procedure

$DPLL(F)$

$F := BCP(F)$

boolean constraint propagation

if $F = \top$ **return** satisfiable

if $\perp \in F$ **return** unsatisfiable

pick remaining variable x and literal $l \in \{x, \neg x\}$

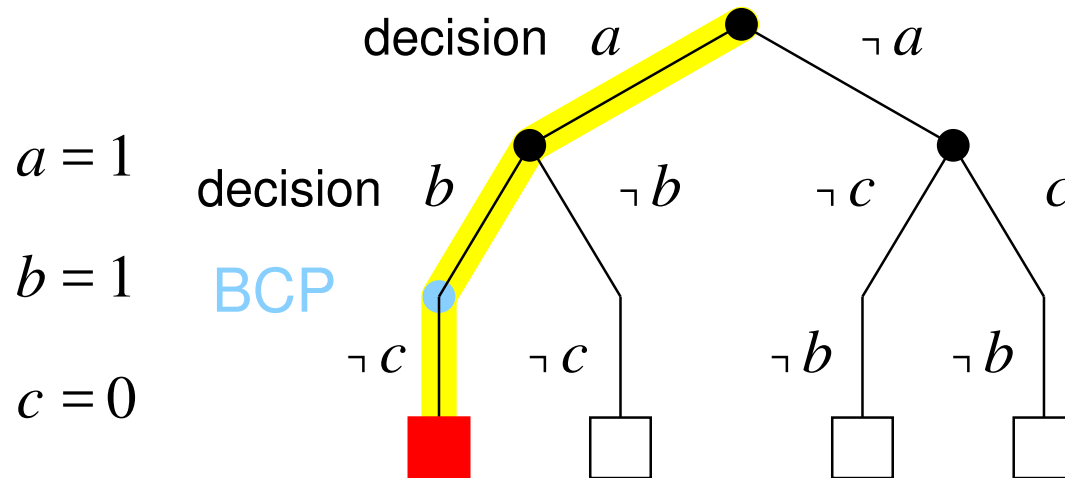
if $DPLL(F \wedge \{l\})$ returns satisfiable **return** satisfiable

return $DPLL(F \wedge \{\neg l\})$

\Rightarrow

CDCL

DPLL Example



clauses

$\neg a \vee \neg b \vee \neg c$

$\neg a \vee \neg b \vee c$

$\neg a \vee b \vee \neg c$

$\neg a \vee b \vee c$

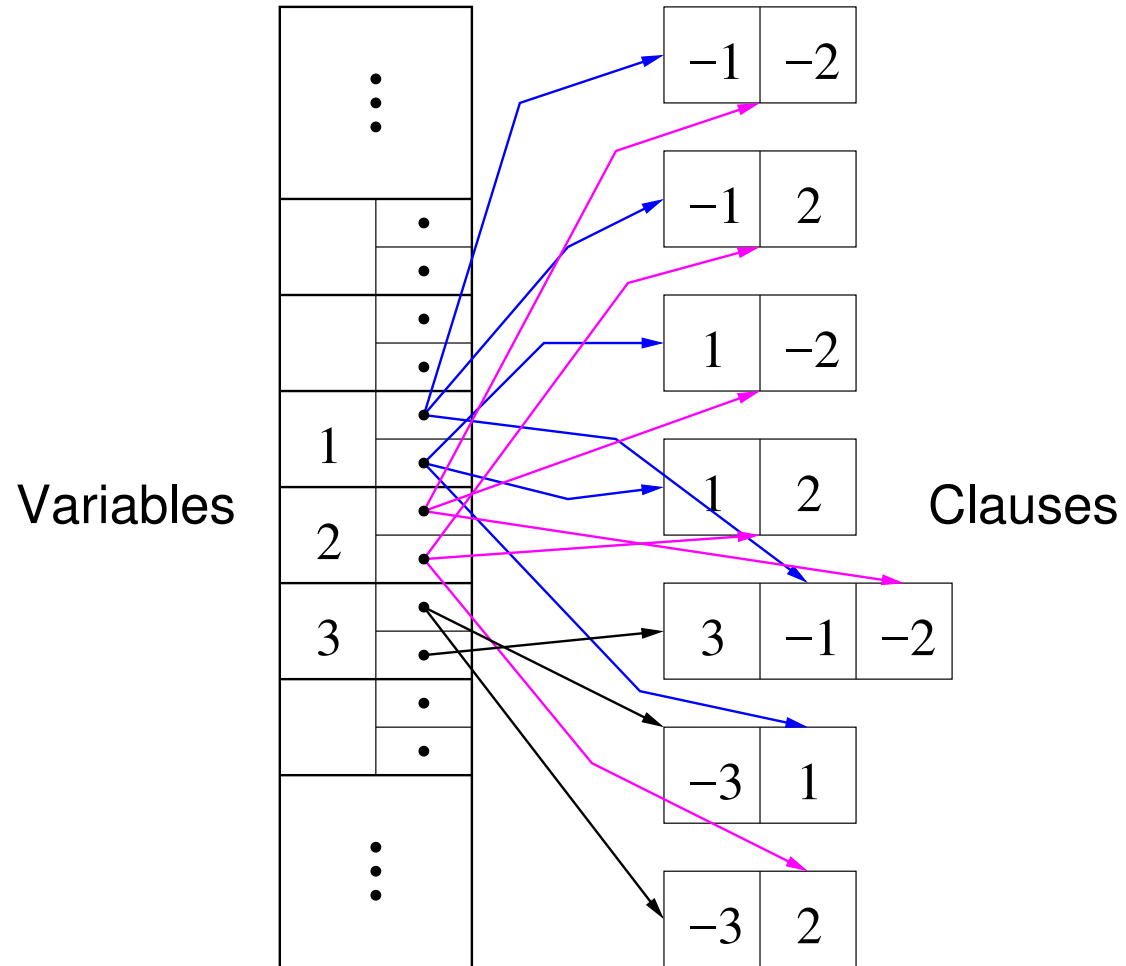
$a \vee \neg b \vee \neg c$

$a \vee \neg b \vee c$

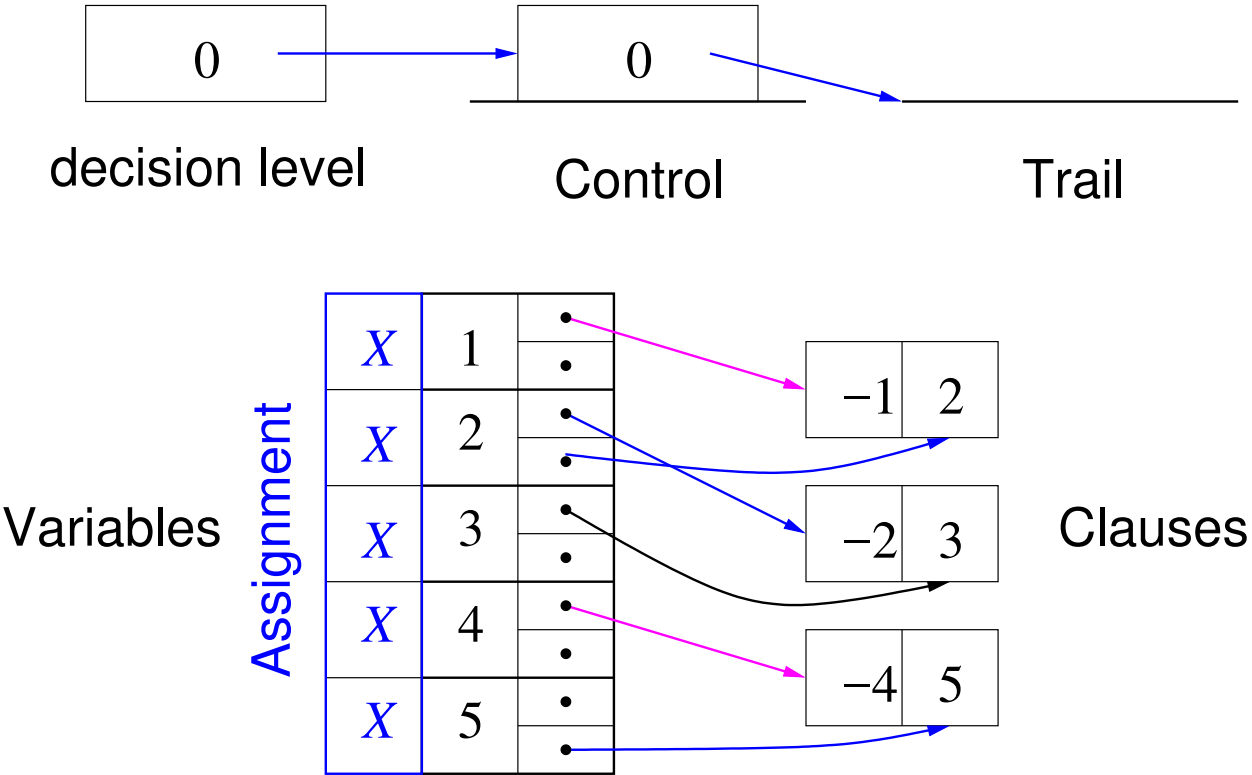
$a \vee b \vee \neg c$

$a \vee b \vee c$

Simple Data Structures in DPLL Implementation

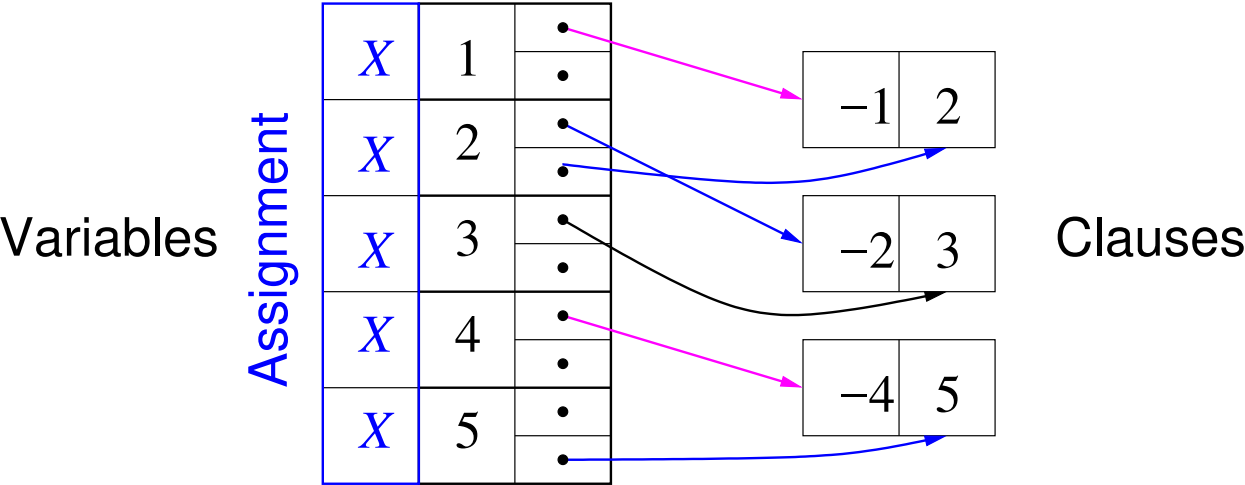
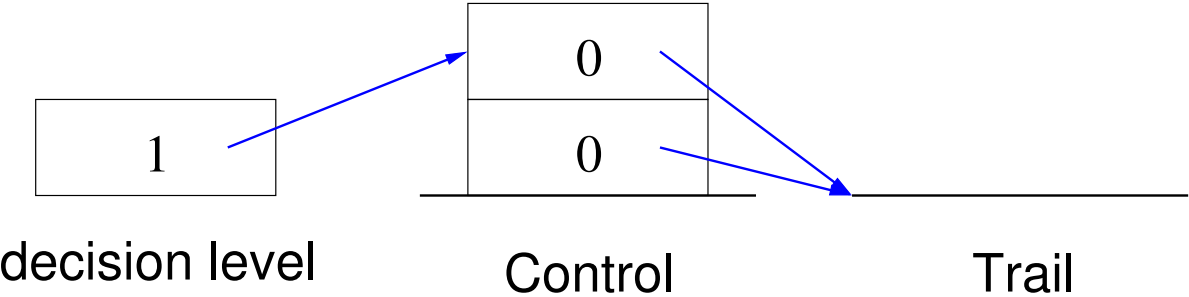


BCP Example



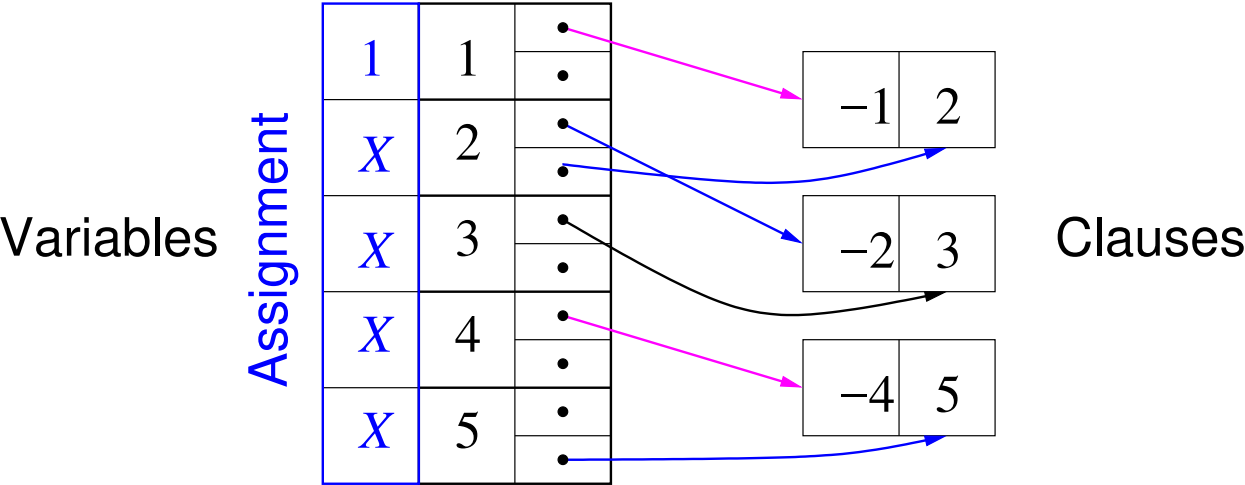
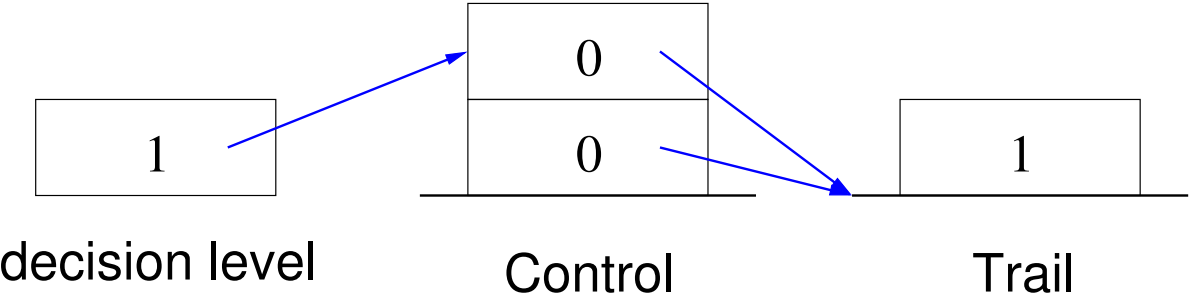
Example cont.

Decide



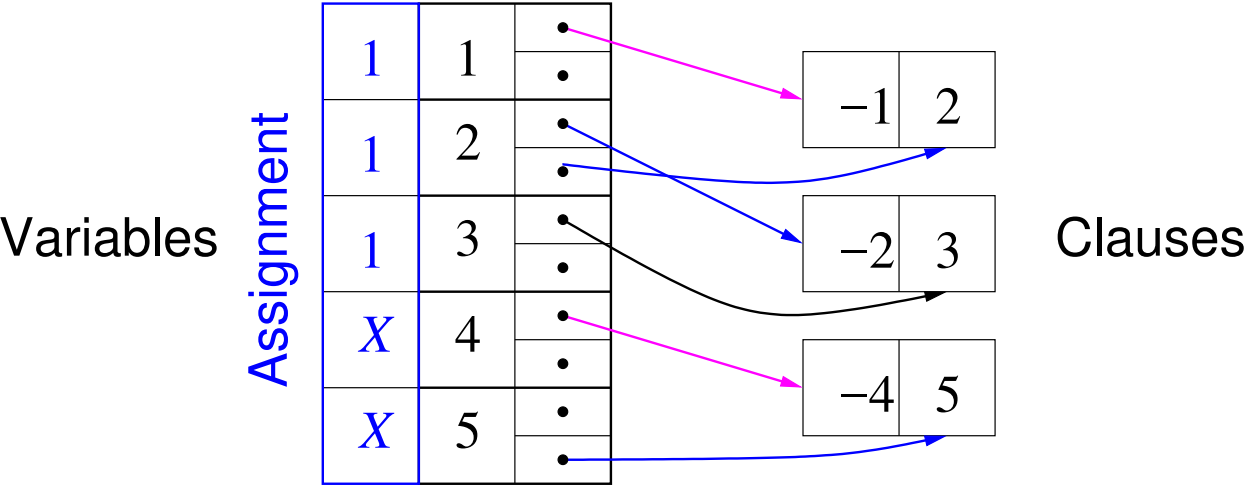
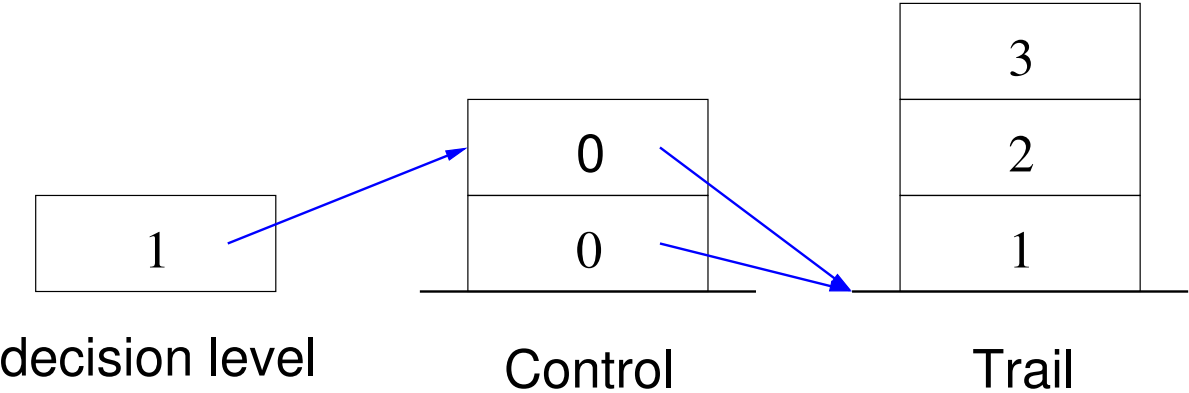
Example cont.

Assign



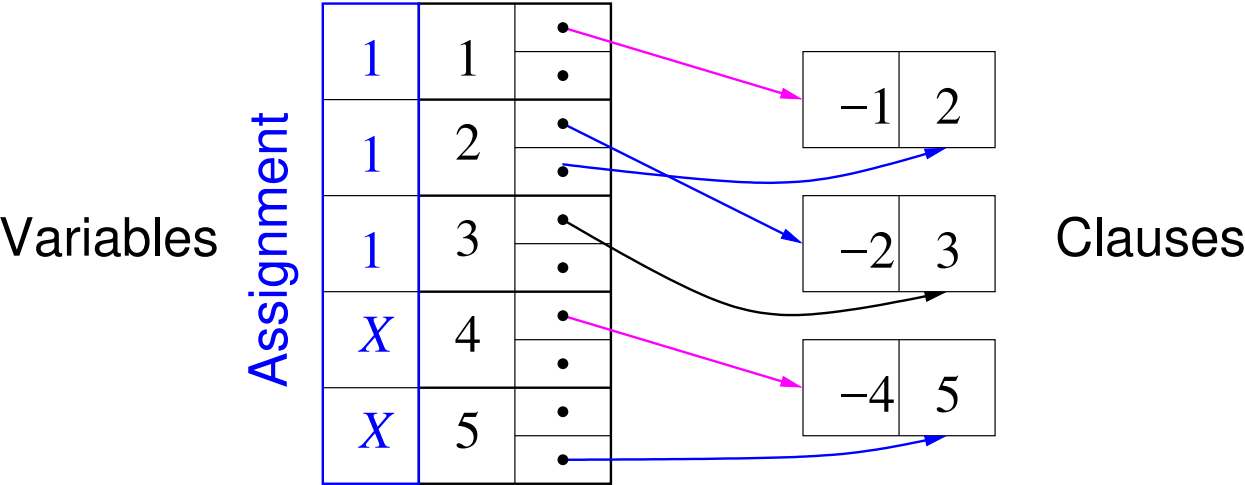
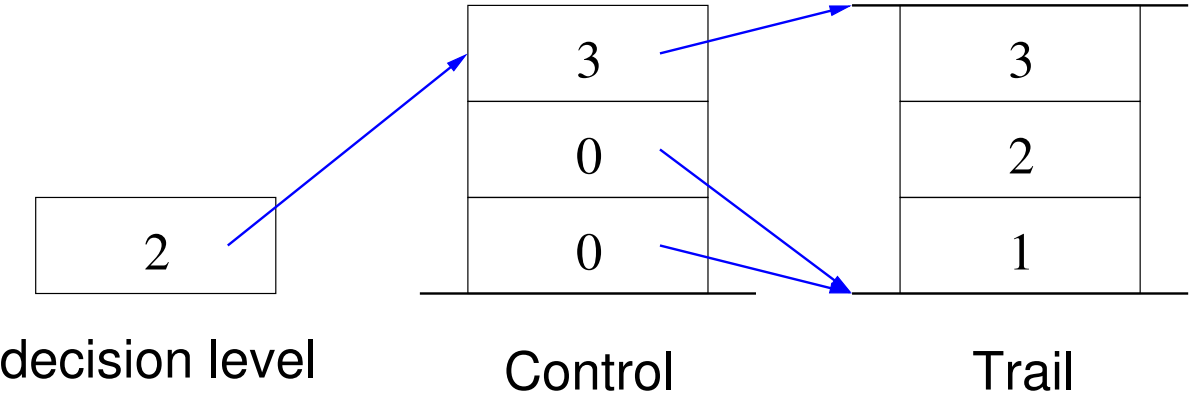
Example cont.

BCP

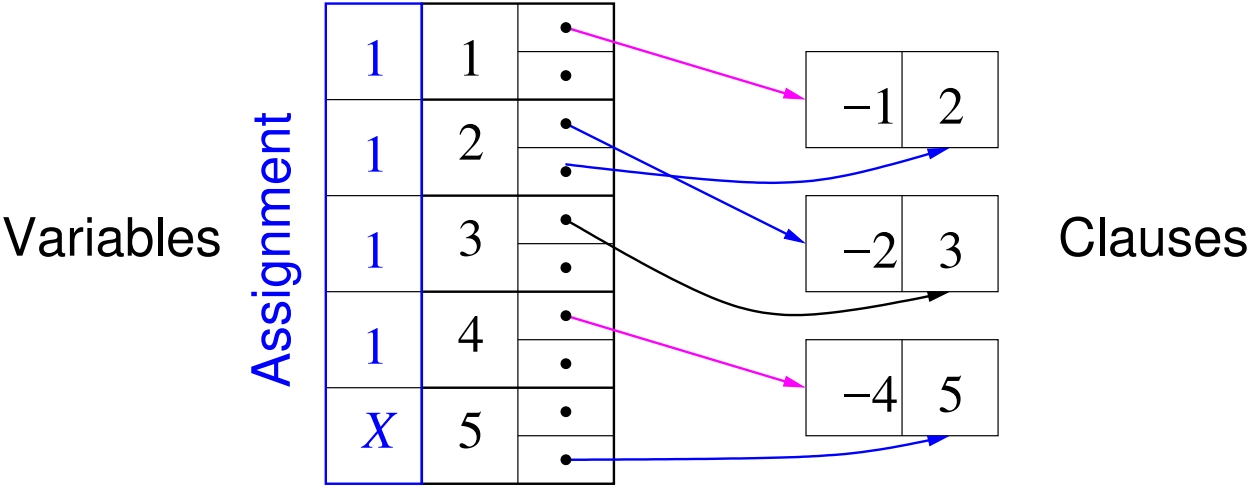
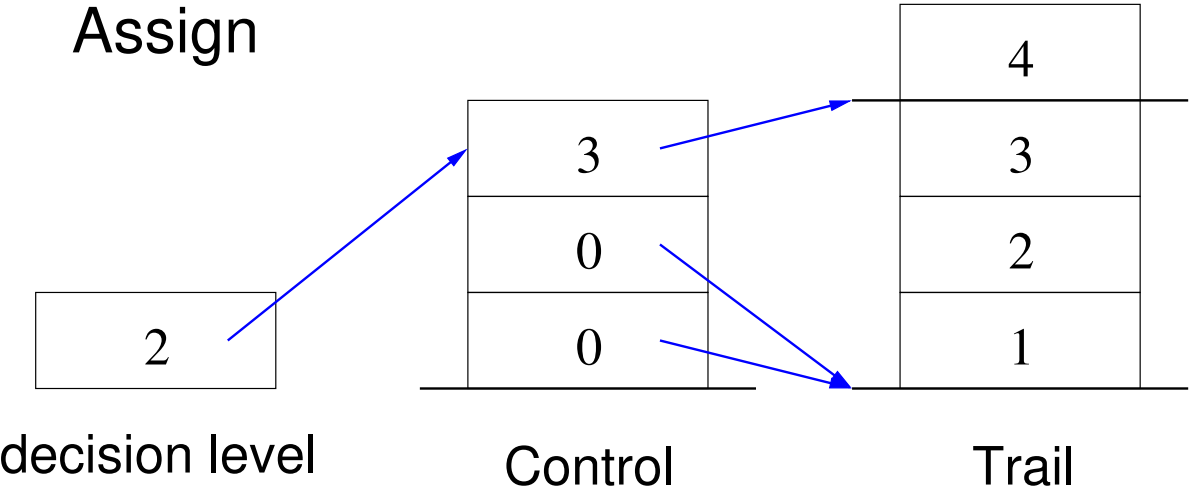


Example cont.

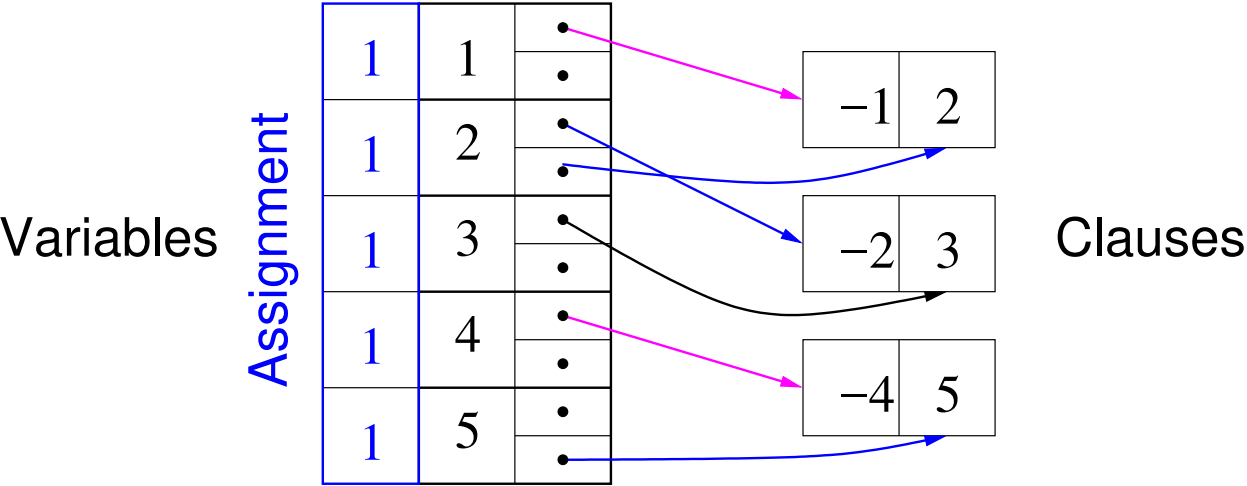
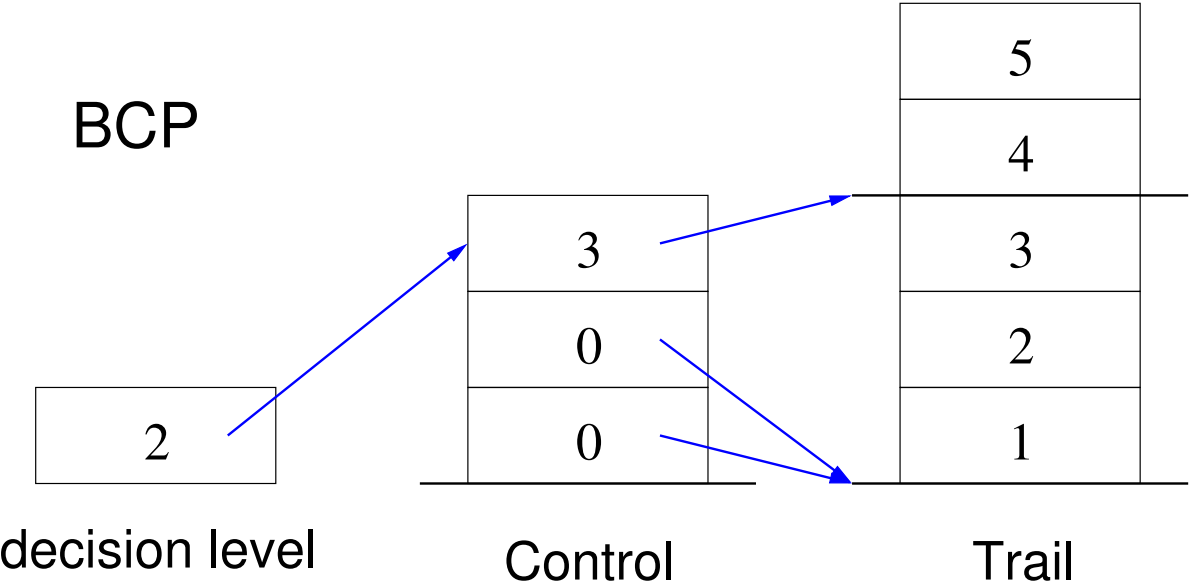
Decide



Example cont.



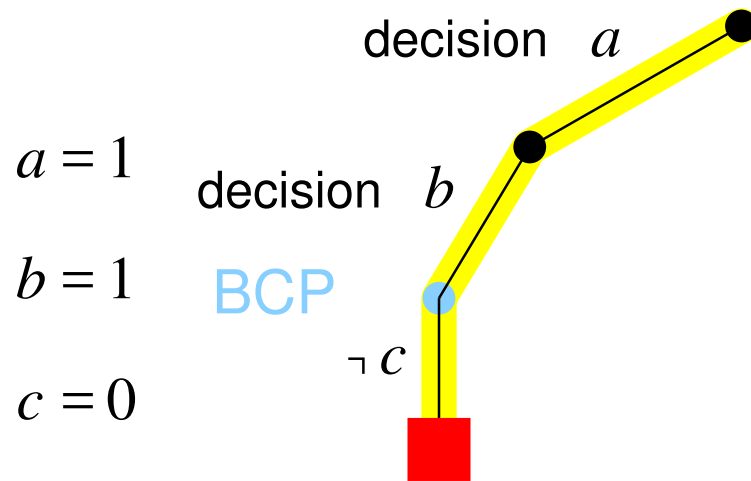
Example cont.



Conflict Driven Clause Learning (CDCL)

- first implemented in the context of GRASP SAT solver [MarqueSilvaSakallah'96]
 - name given later to distinguish it from DPLL
 - not recursive anymore
- essential for SMT
- learning clauses as no-goods
- notion of implication graph
- (first) unique implication points

Conflict Driven Clause Learning (CDCL)



clauses

$\neg a \vee \neg b \vee \neg c$

$\neg a \vee \neg b \vee c$

$\neg a \vee b \vee \neg c$

$\neg a \vee b \vee c$

$a \vee \neg b \vee \neg c$

$a \vee \neg b \vee c$

$a \vee b \vee \neg c$

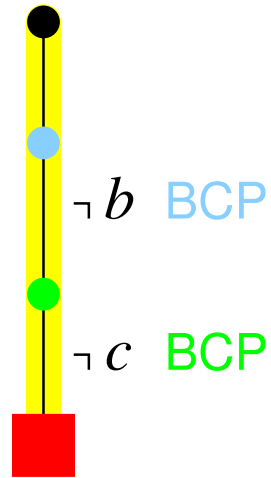
$a \vee b \vee c$

learn $\neg a \vee \neg b$

Conflict Driven Clause Learning (CDCL)

$$a = 1$$
$$b = 0$$
$$c = 0$$

decision a

 $\neg b$ BCP $\neg C$ BCP

clauses

$$\neg a \vee \neg b \vee \neg c$$
$$\neg a \vee \neg b \vee c$$
$$\neg a \vee b \vee \neg c$$
$$\neg a \vee b \vee c$$
$$a \vee \neg b \vee \neg c$$
$$a \vee \neg b \vee c$$
$$a \vee b \vee \neg c$$
$$a_v \quad b_v \quad c$$
$$\neg a \vee \neg b$$

learn

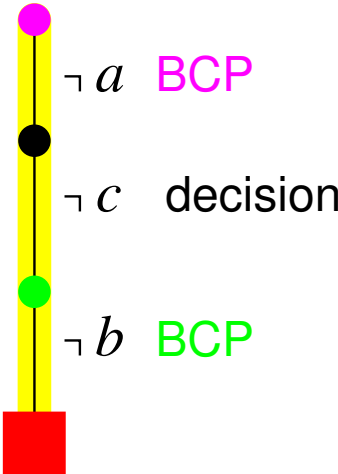
 $\neg a$

Conflict Driven Clause Learning (CDCL)

$a = 1$

$b = 0$

$c = 0$



clauses

$\neg a \vee \neg b \vee \neg c$

$\neg a \vee \neg b \vee c$

$\neg a \vee b \vee \neg c$

$\neg a \vee b \vee c$

$a \vee \neg b \vee \neg c$

$a \vee \neg b \vee c$

$a \vee b \vee \neg c$

$a \vee b \vee c$

$\neg a \vee \neg b$

$\neg a$

learn

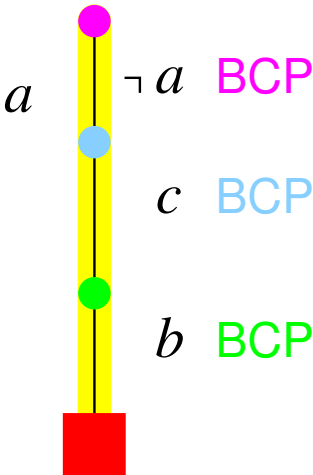
c

Conflict Driven Clause Learning (CDCL)

$a = 1$

$b = 0$

$c = 0$



clauses

$\neg a \vee \neg b \vee \neg c$

$\neg a \vee \neg b \vee c$

$\neg a \vee b \vee \neg c$

$\neg a \vee b \vee c$

$a \vee \neg b \vee \neg c$

$a \vee \neg b \vee c$

$a \vee b \vee \neg c$

$a \vee b \vee c$

$\neg a \vee \neg b$

$\neg a$

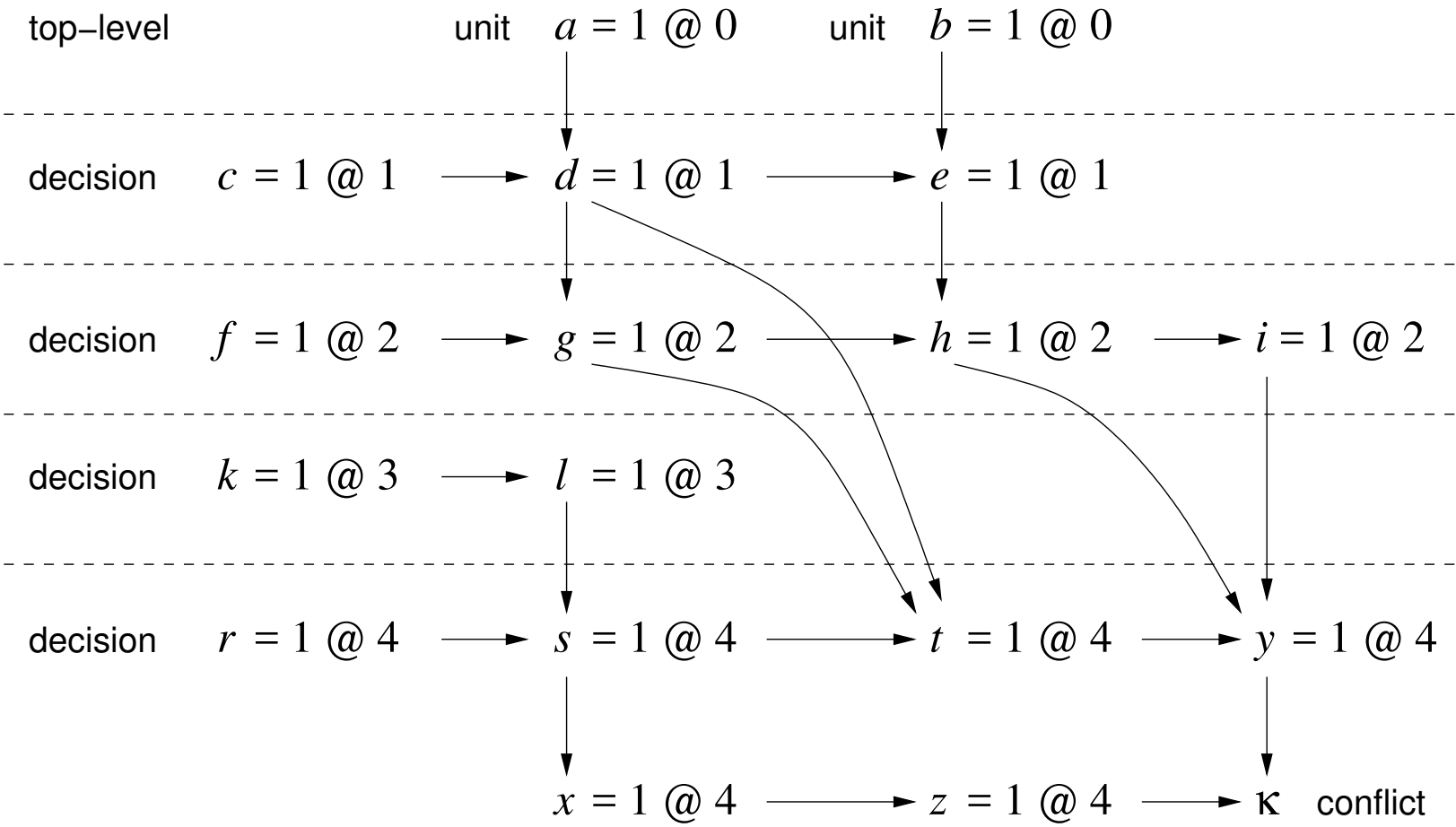
c

learn

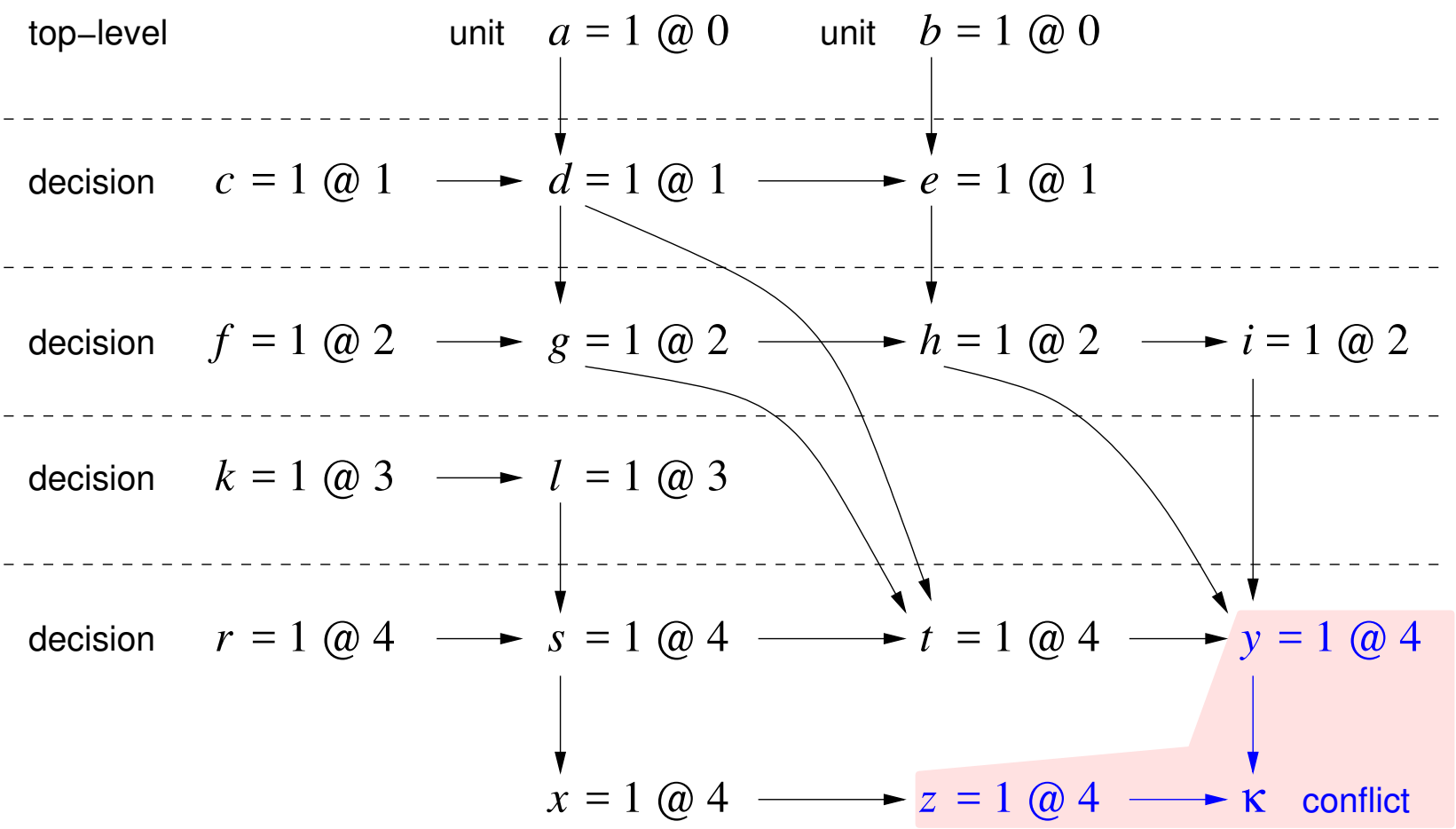
\perp

empty clause

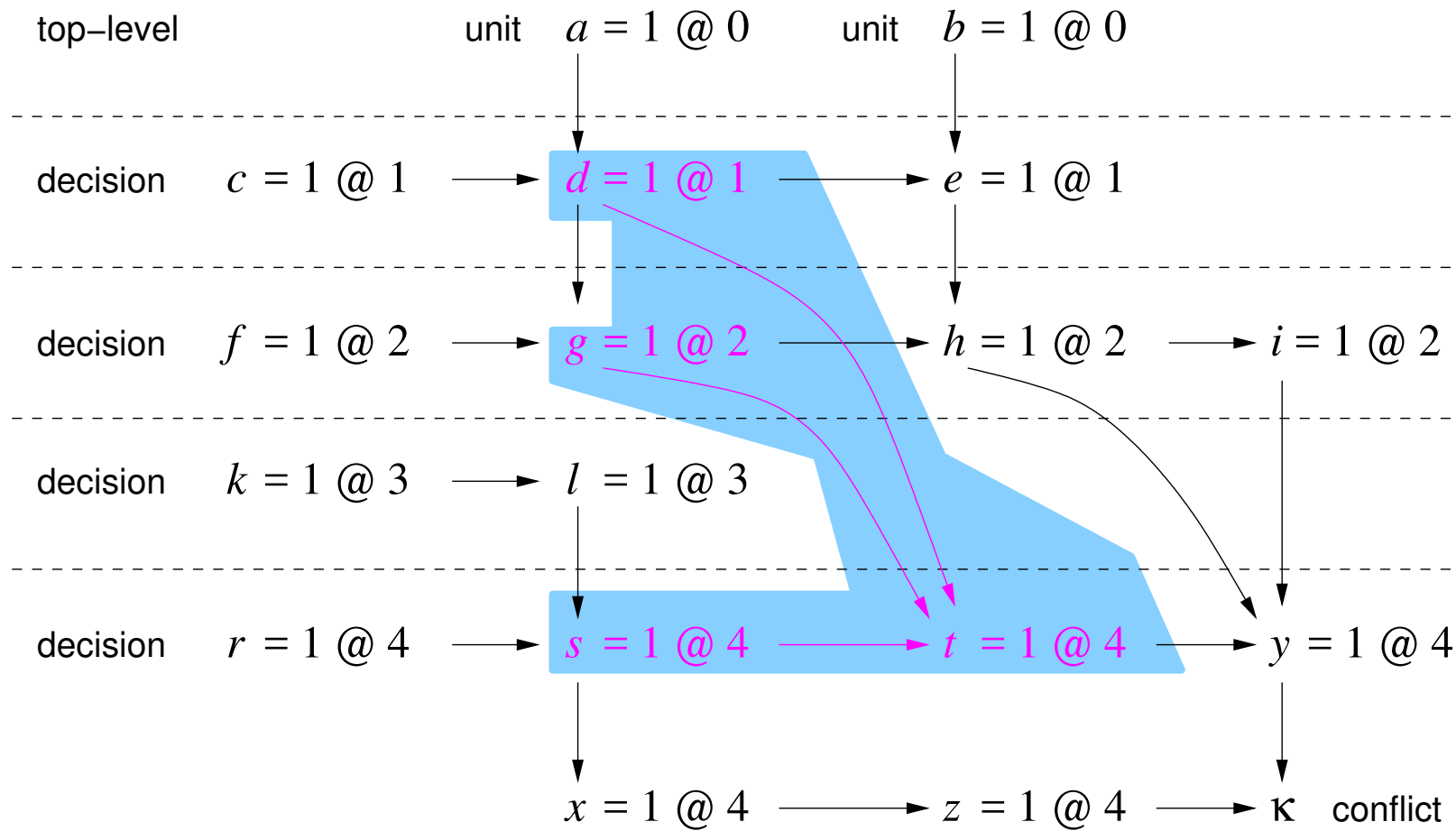
Implication Graph



Conflict

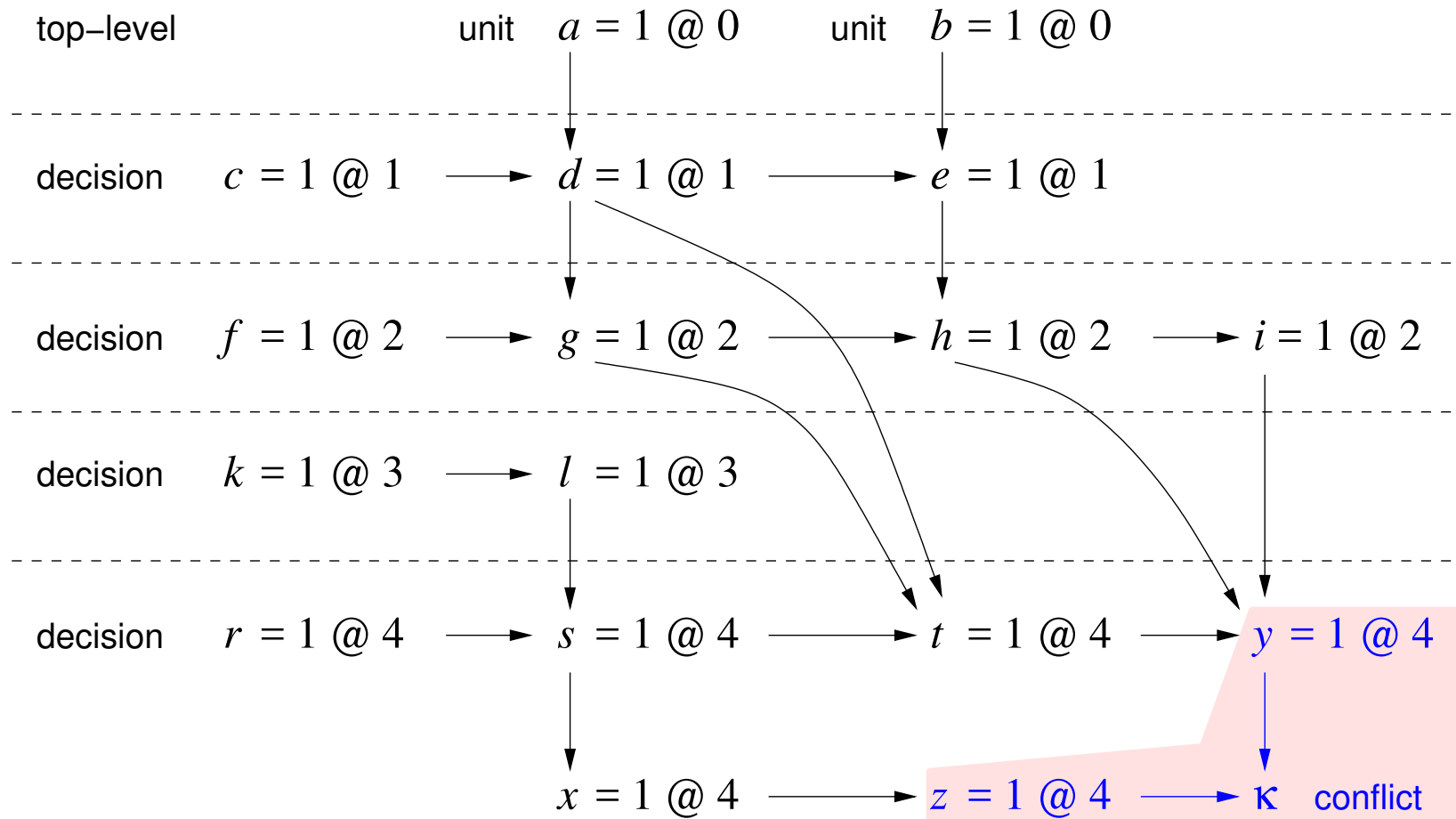


Antecedents / Reasons



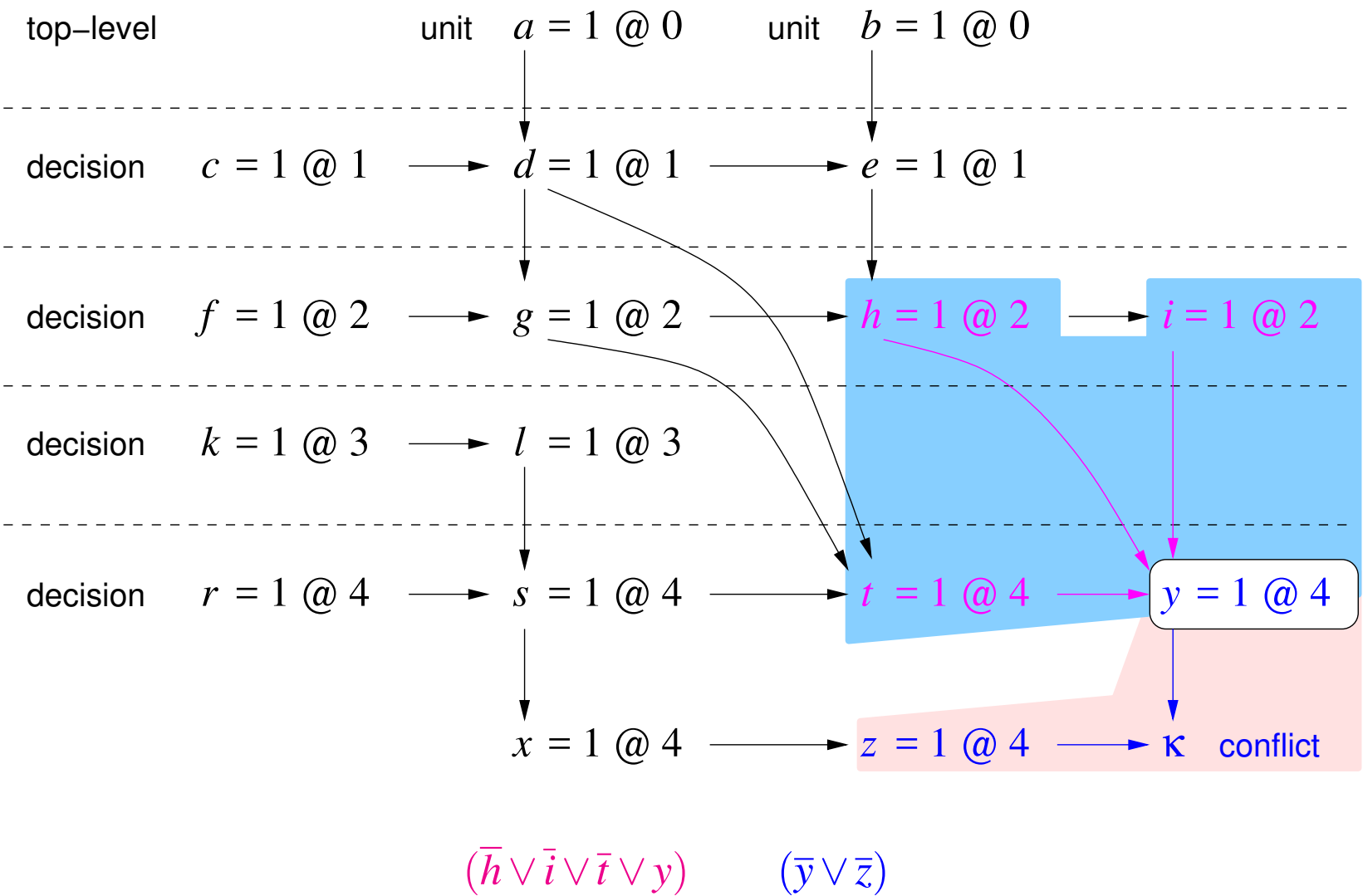
$$d \wedge g \wedge s \rightarrow t \quad \equiv \quad (\bar{d} \vee \bar{g} \vee \bar{s} \vee t)$$

Conflicting Clauses

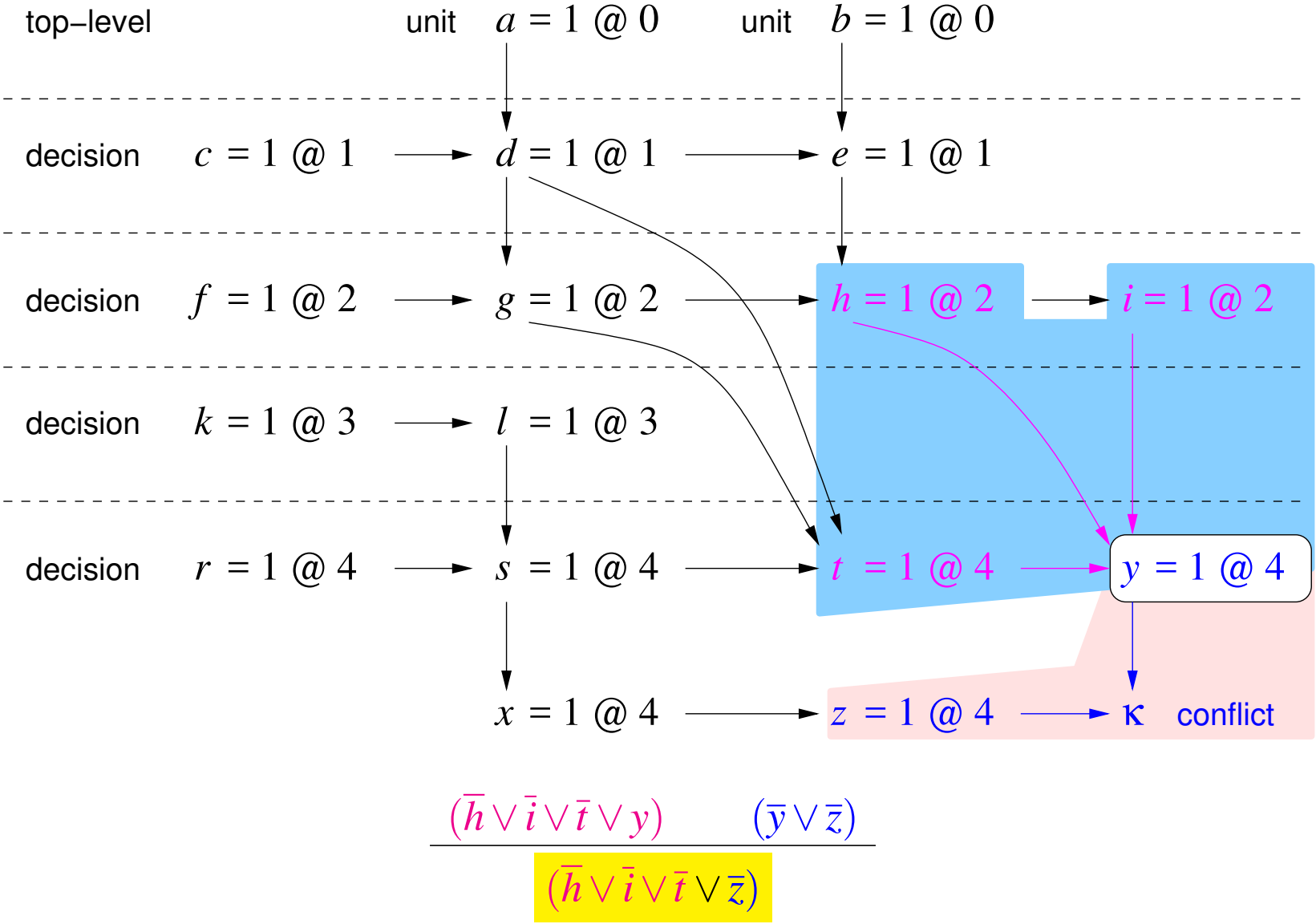


$$\neg(y \wedge z) \quad \equiv \quad (\bar{y} \vee \bar{z})$$

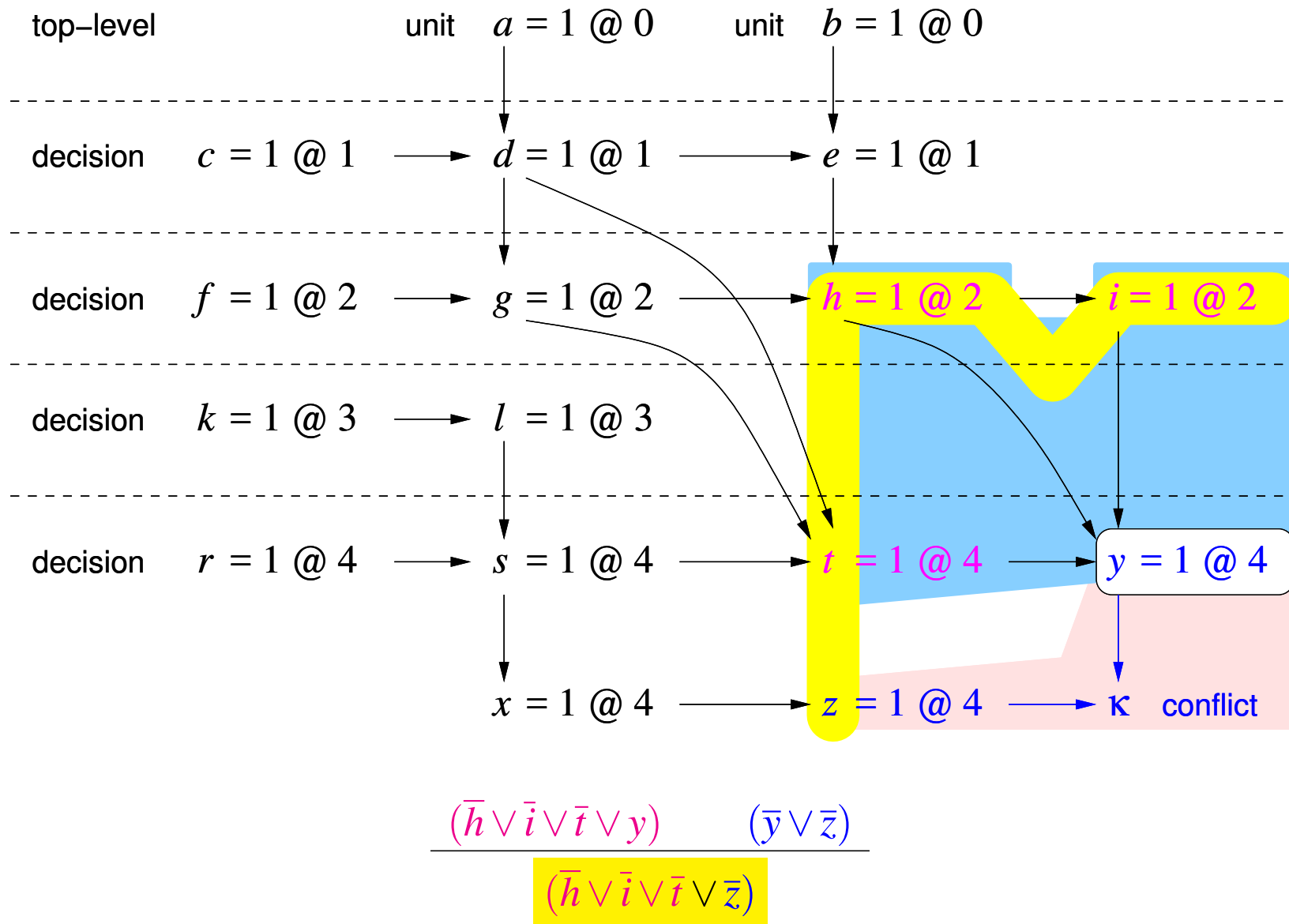
Resolving Antecedents 1st Time



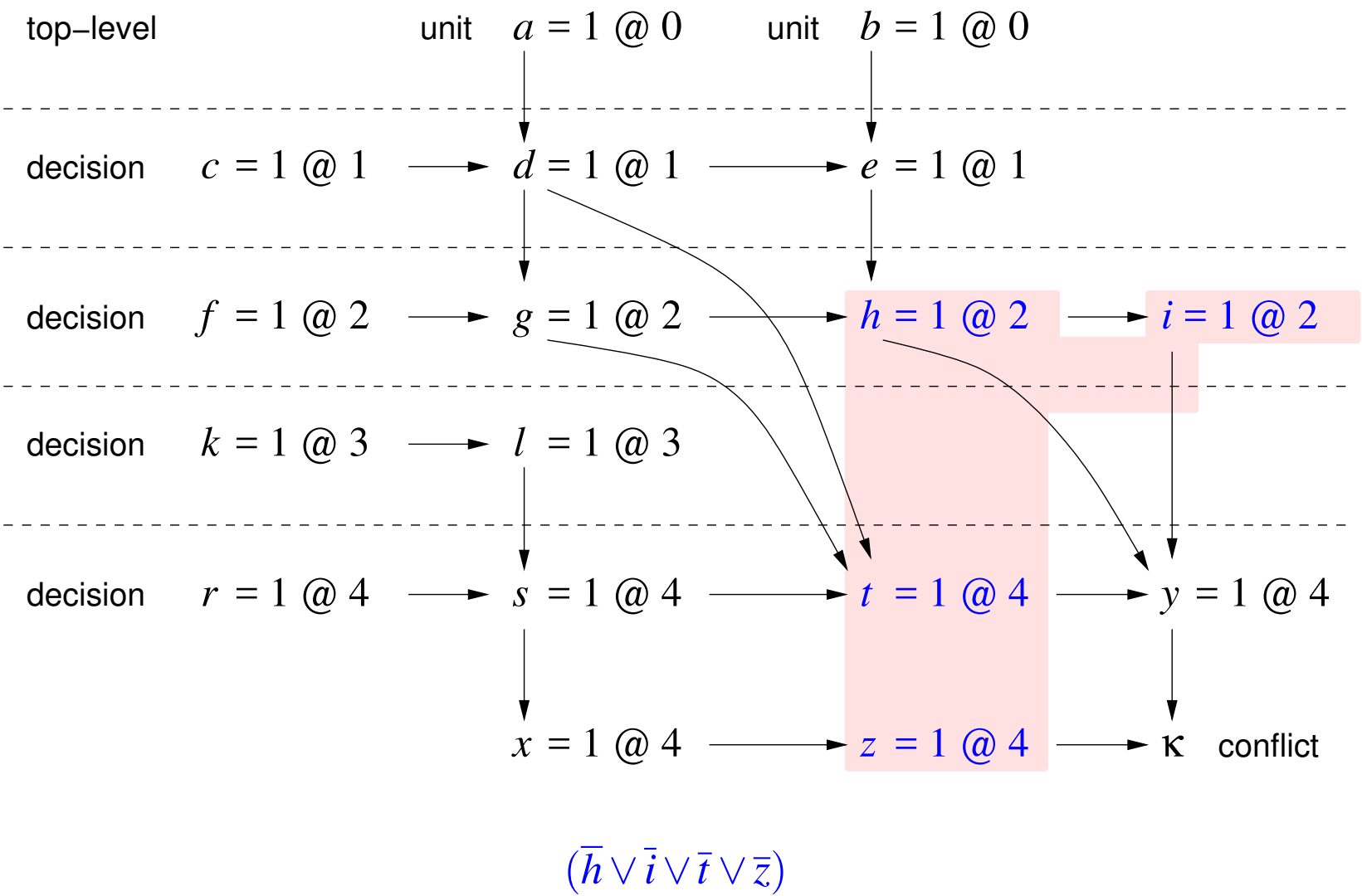
Resolving Antecedents 1st Time



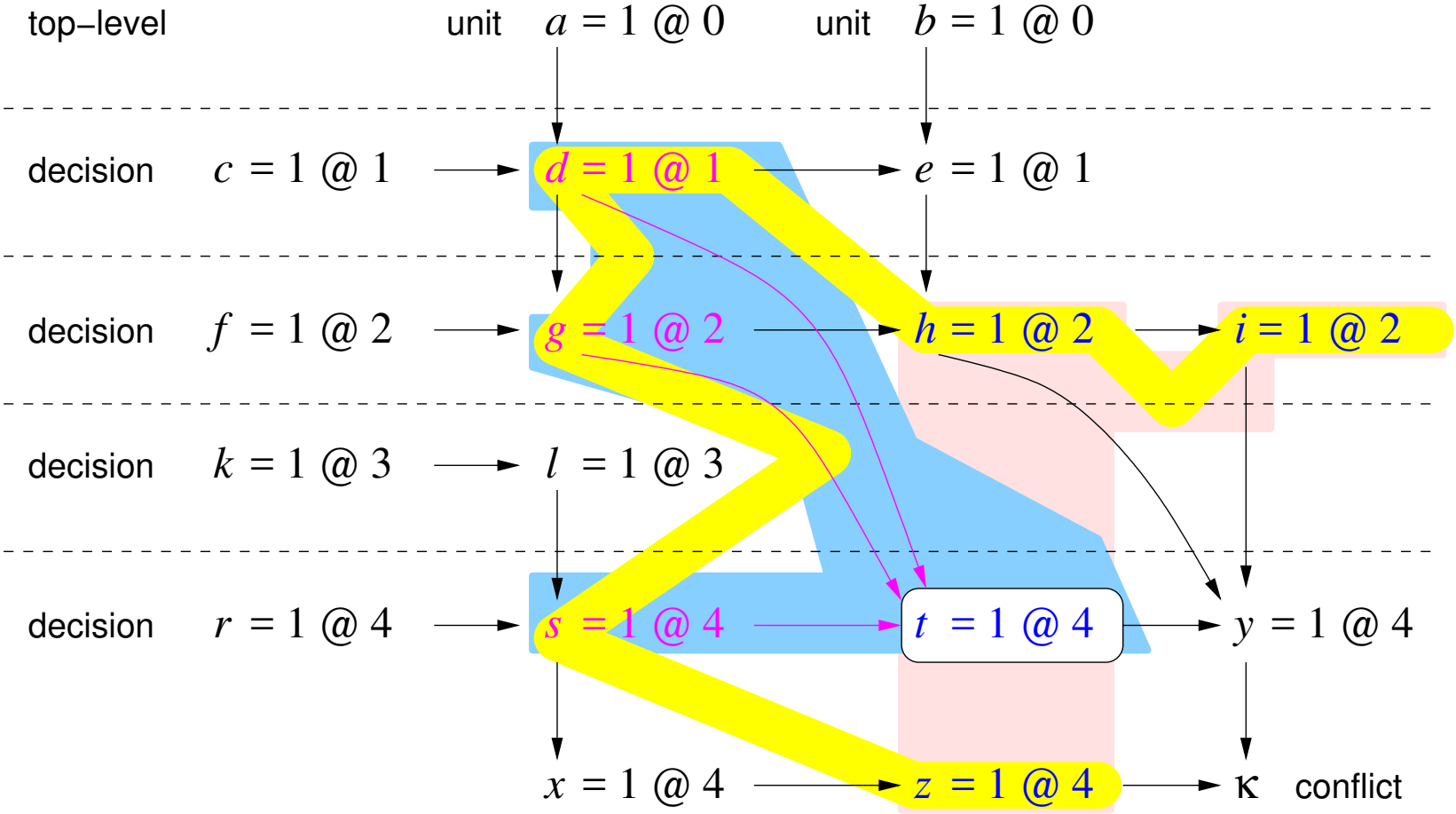
Resolvents = **Cuts** = Potential Learned Clauses



Potential Learned Clause After 1 Resolution

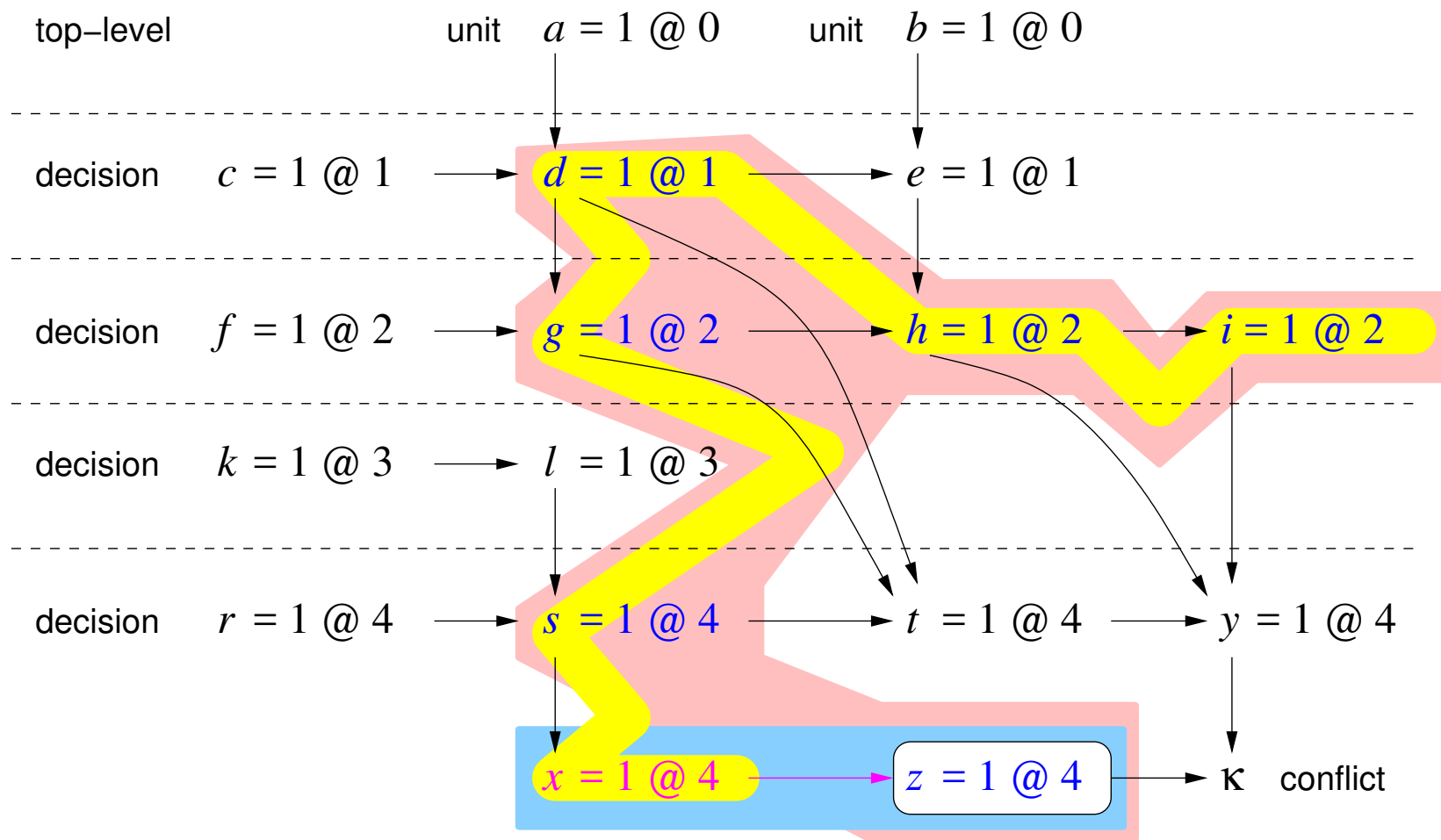


Resolving Antecedents 2nd Time



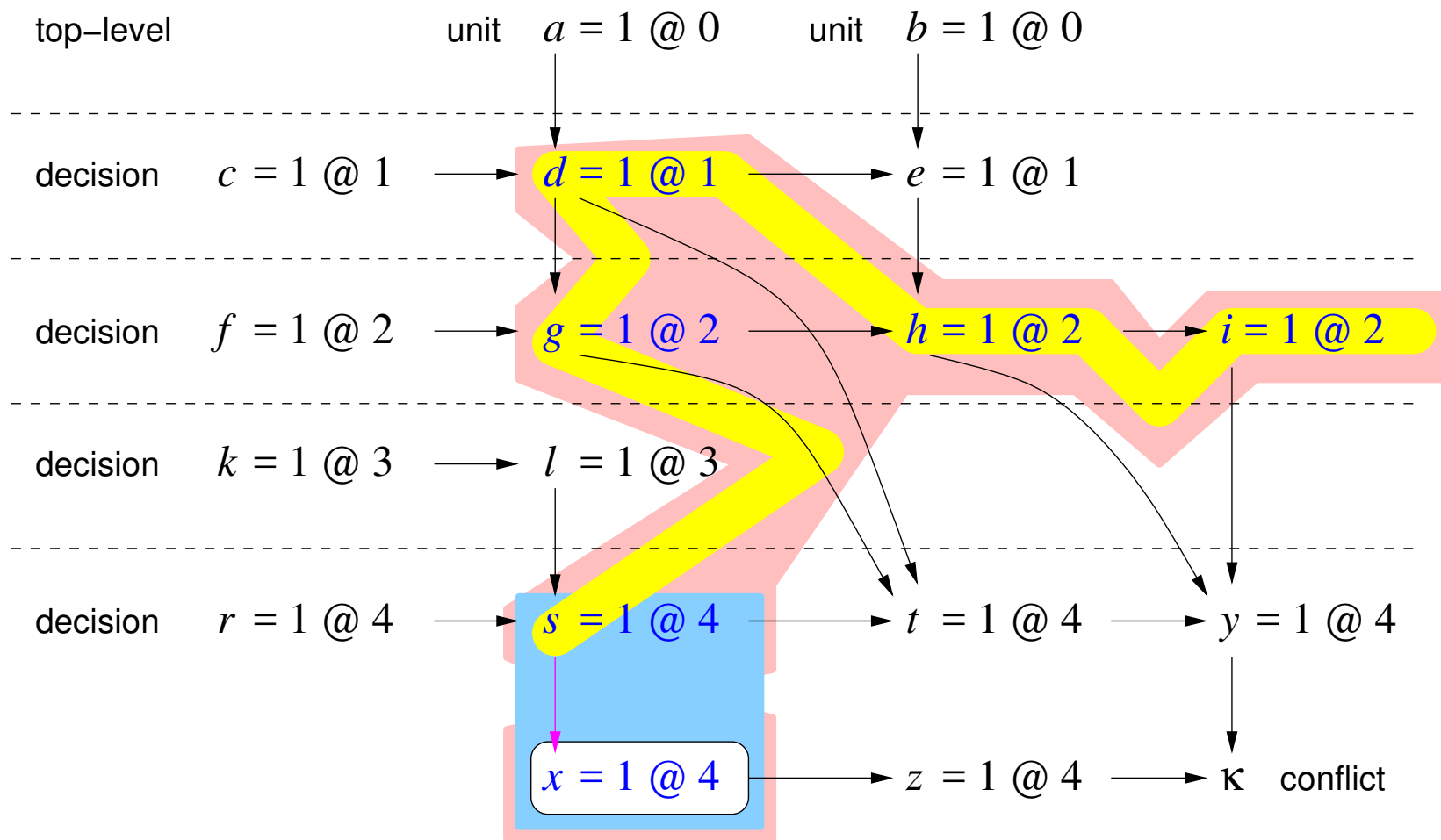
$$\frac{(\bar{d} \vee \bar{g} \vee \bar{s} \vee t) \quad (\bar{h} \vee \bar{i} \vee \bar{t} \vee \bar{z})}{(\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i} \vee \bar{z})}$$

Resolving Antecedents 3rd Time



$$\frac{(\bar{x} \vee z) \quad (\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i} \vee \bar{z})}{(\bar{x} \vee \bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i})}$$

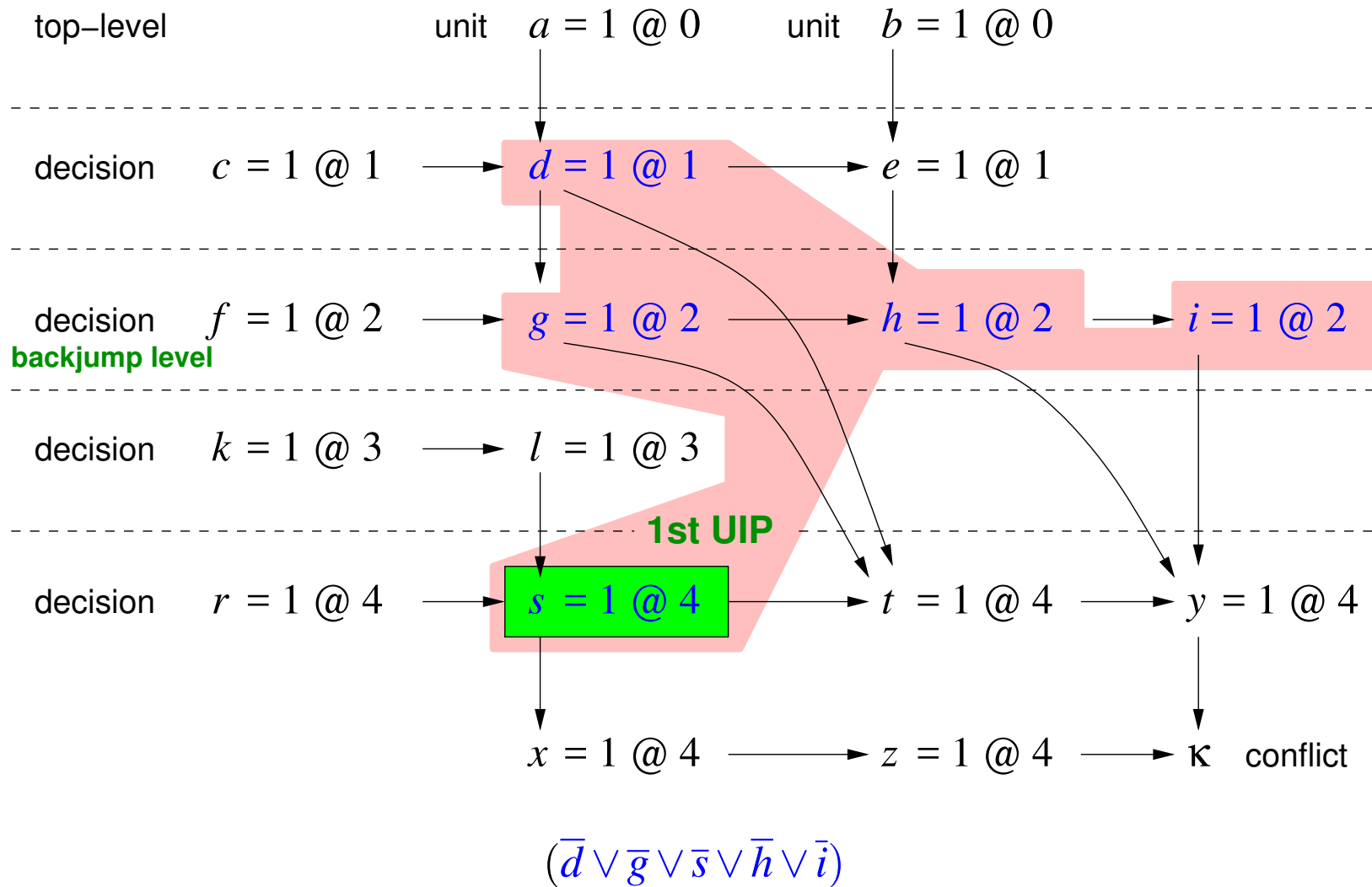
Resolving Antecedents 4th Time



$$\frac{(\bar{s} \vee x) \quad (\bar{x} \vee \bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i})}{(\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i})}$$

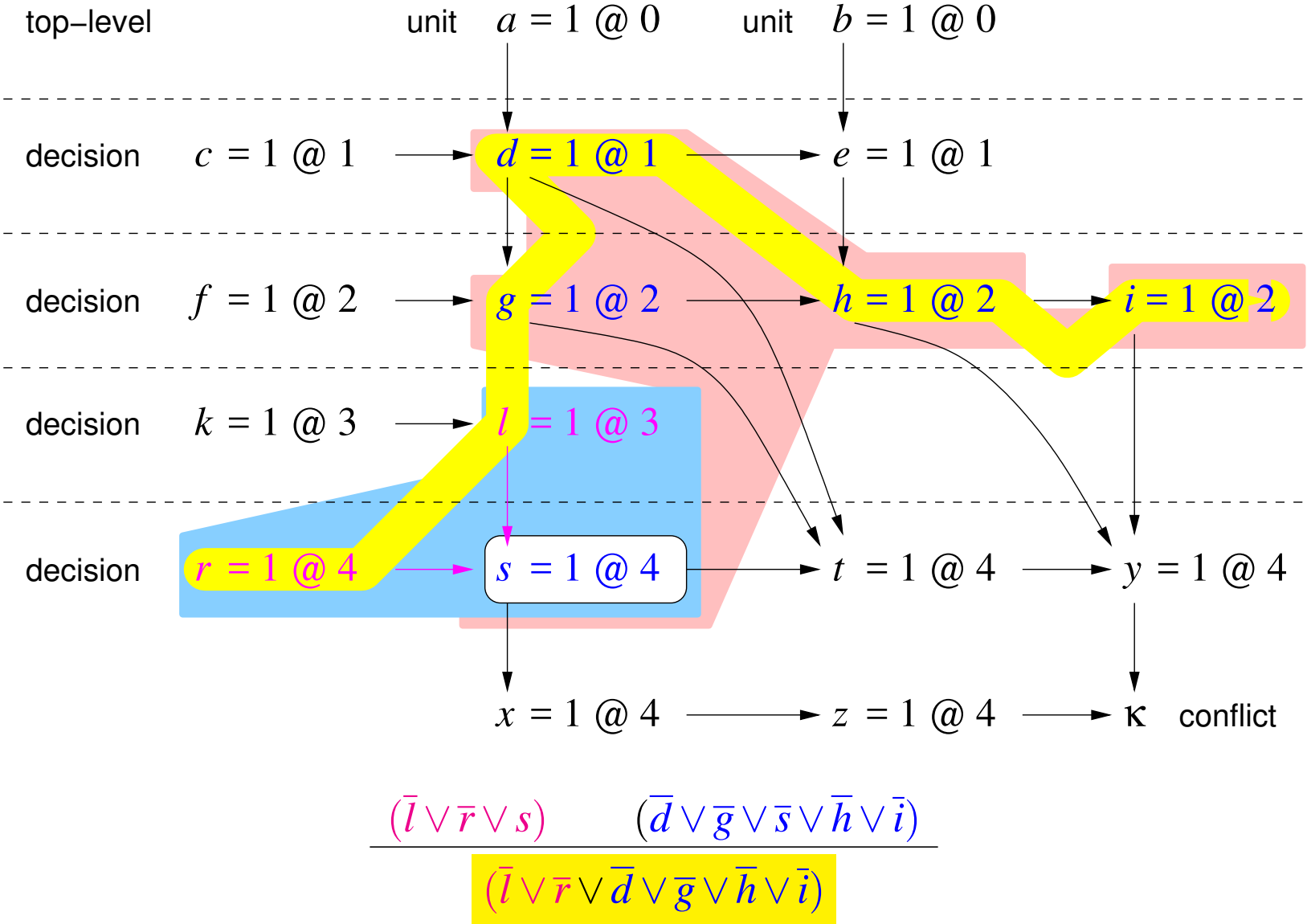
self subsuming resolution

1st UIP Clause after 4 Resolutions

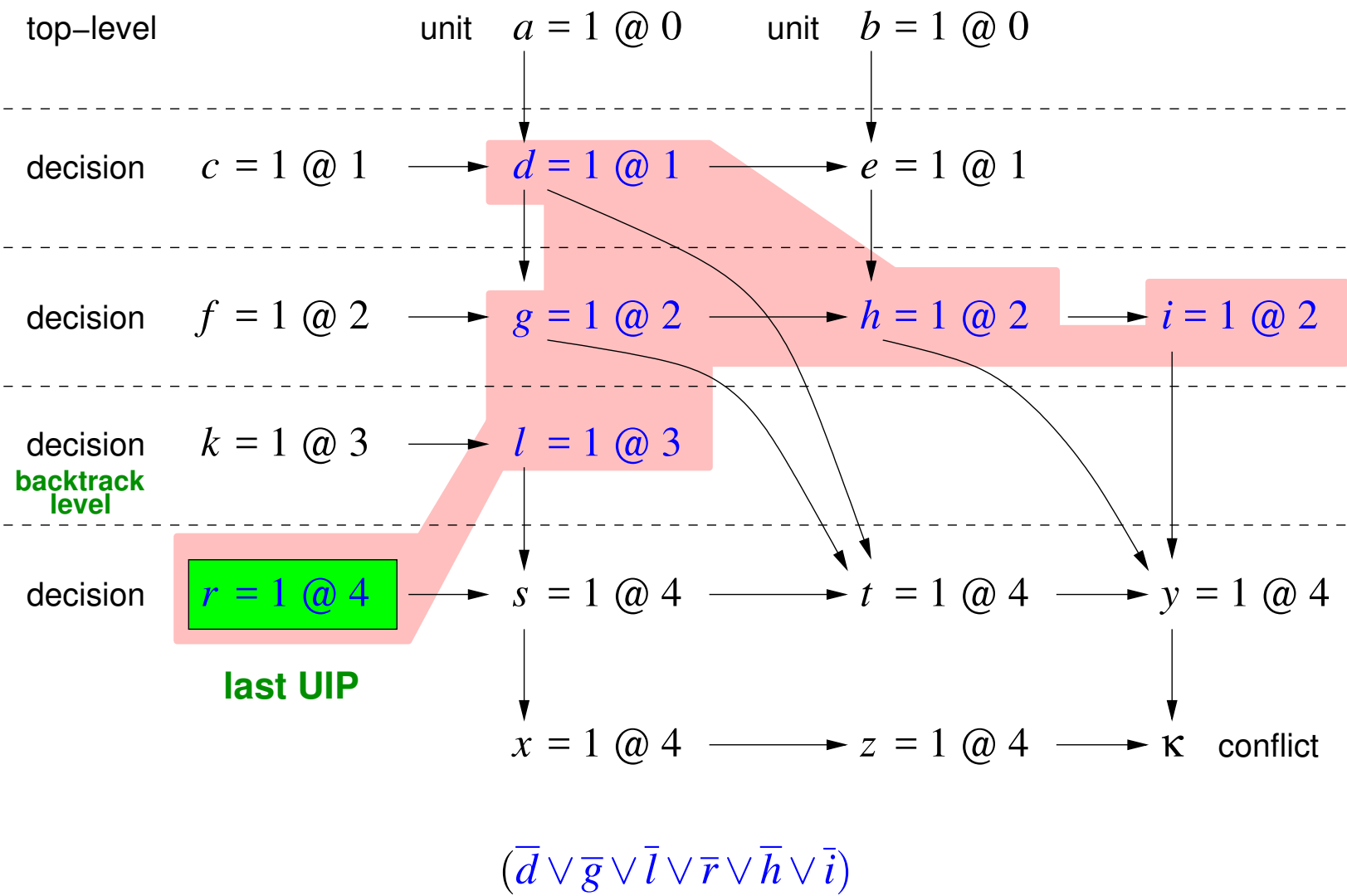


UIP = unique implication point dominates conflict on the last level

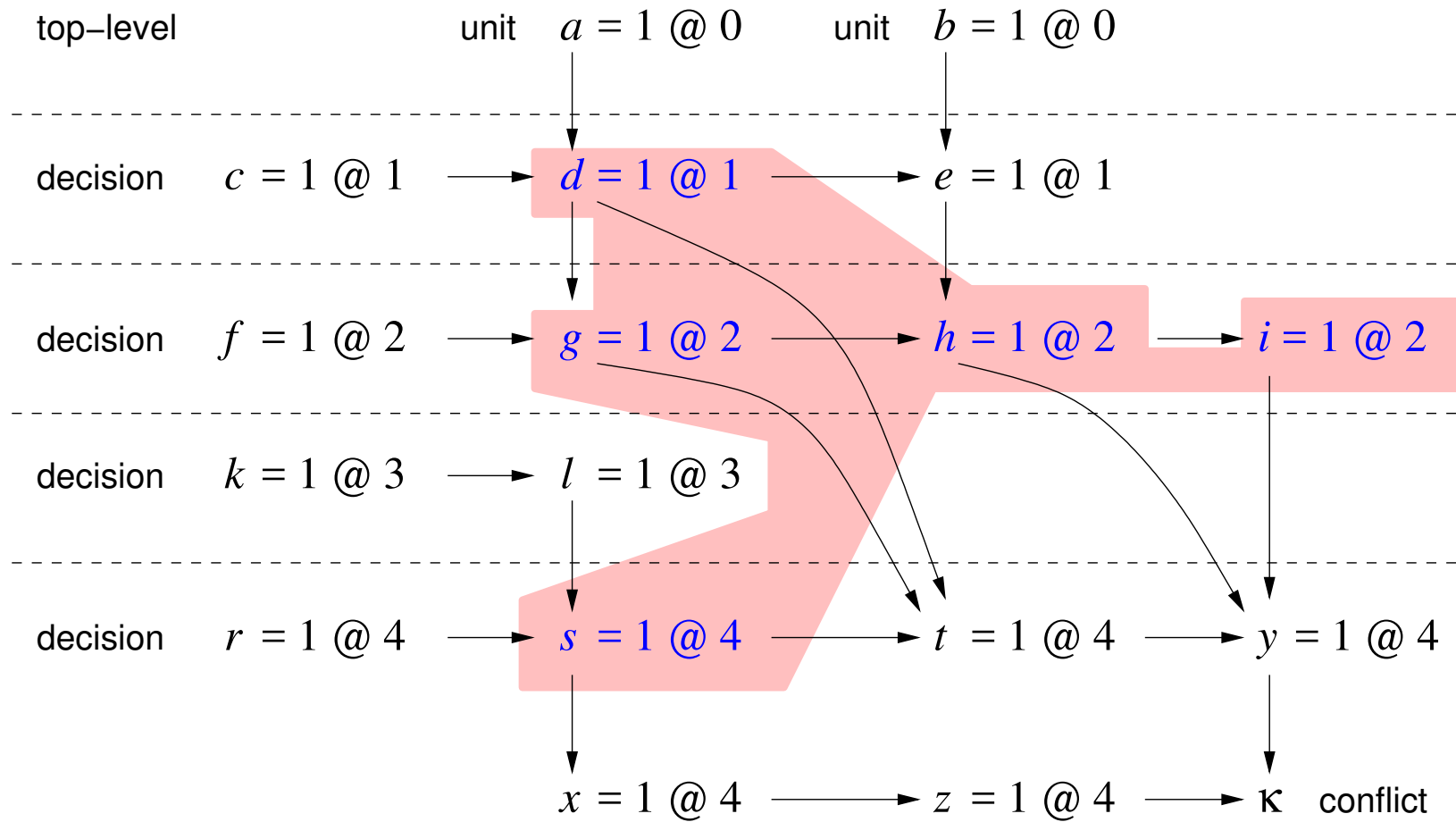
Resolving Antecedents 5th Time



Decision Learned Clause

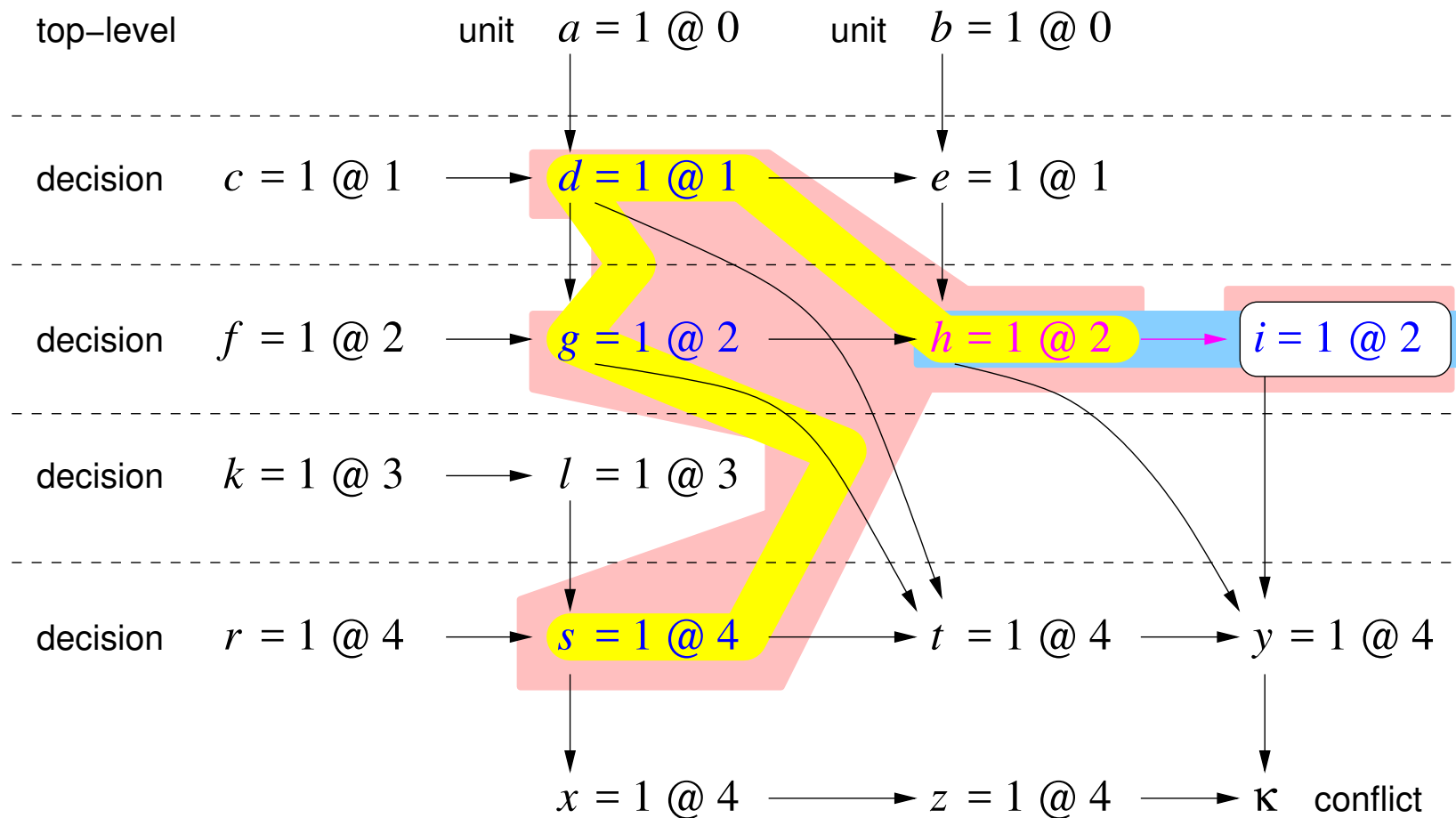


1st UIP Clause after 4 Resolutions



$$(\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i})$$

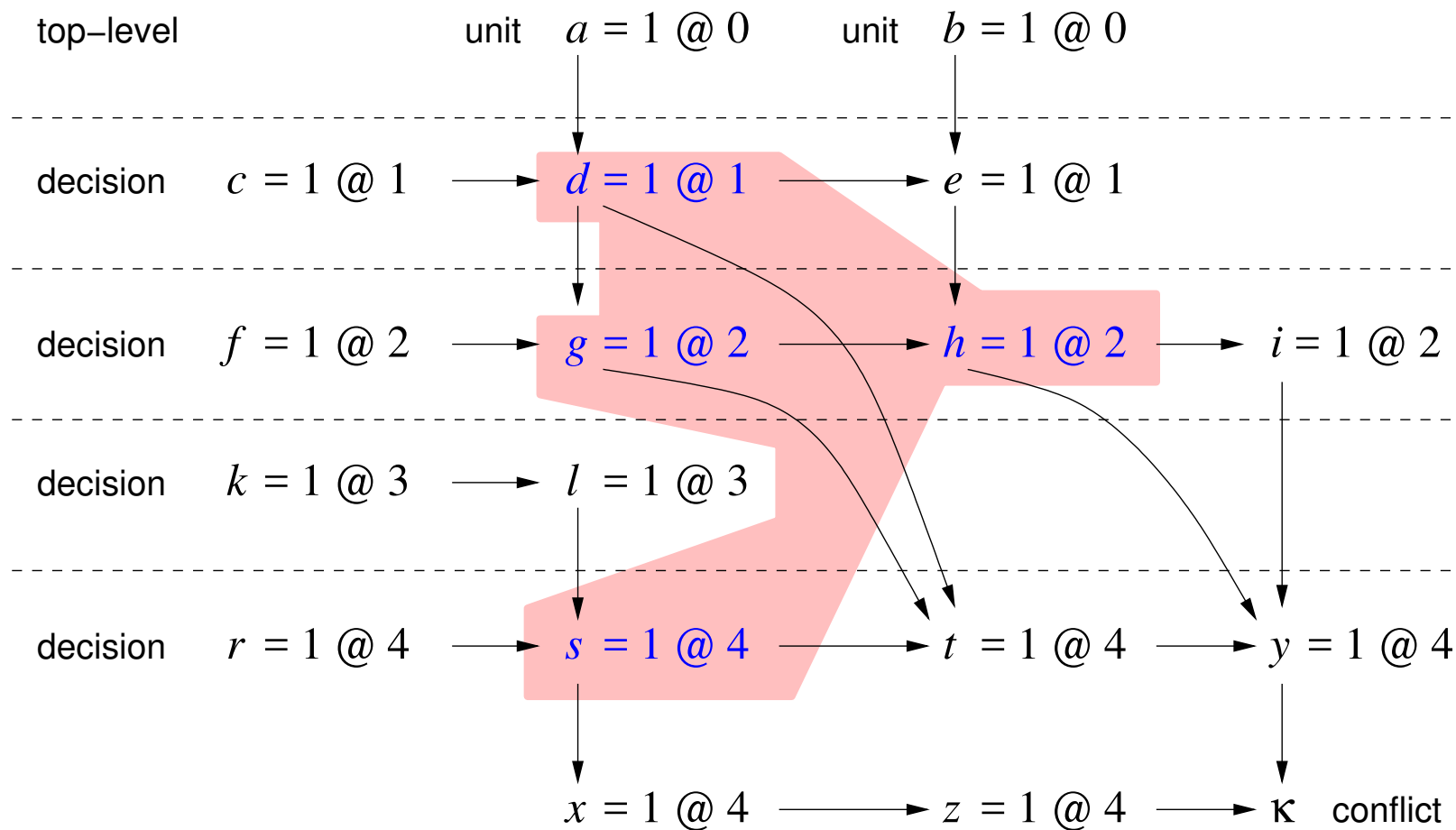
Locally Minimizing 1st UIP Clause



$$\frac{(\bar{h} \vee i) \quad (\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h} \vee \bar{i})}{(\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h})}$$

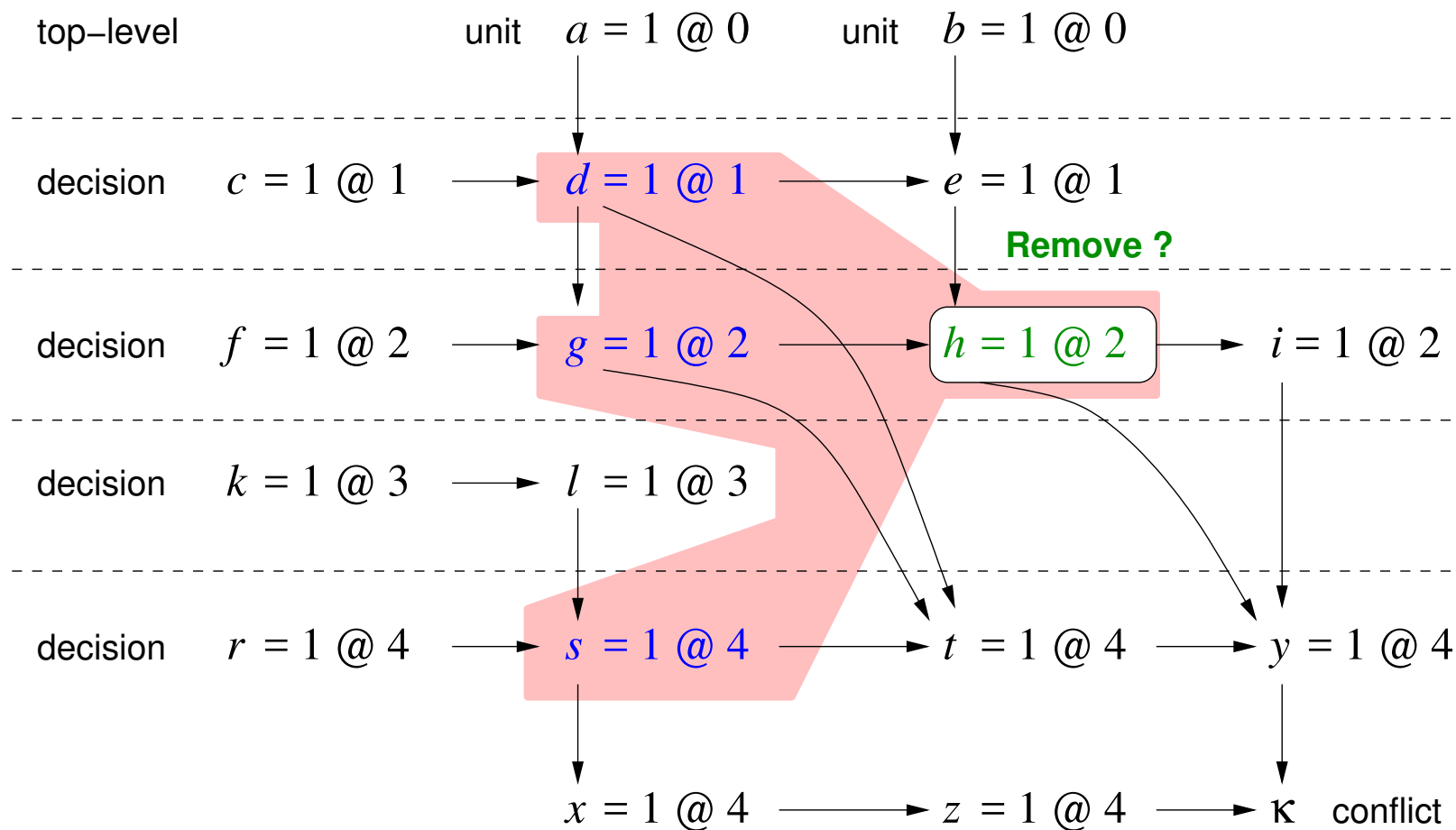
self subsuming resolution

Locally Minimized Learned Clause



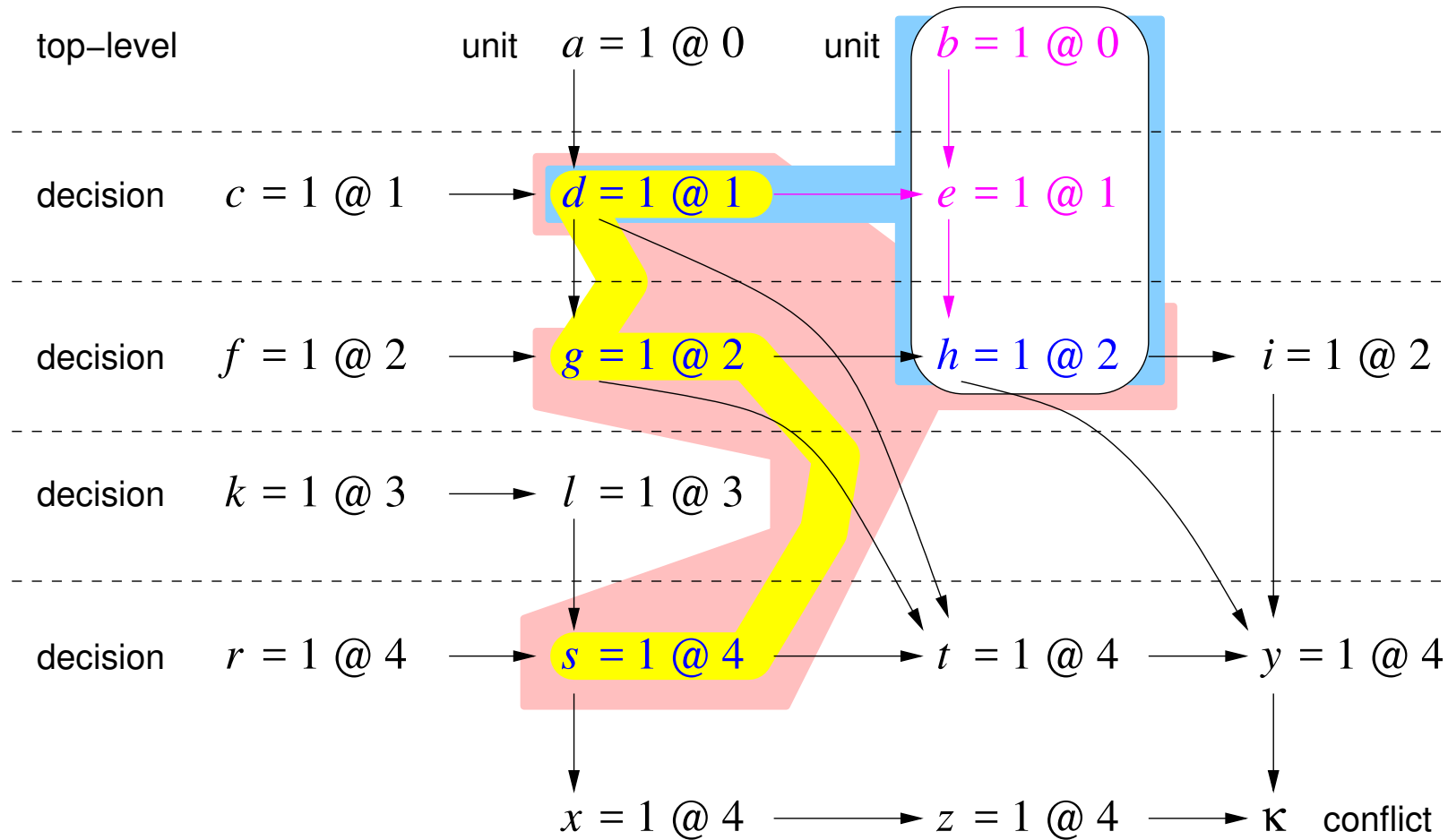
$$(\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h})$$

Minimizing Locally Minimized Learned Clause Further?



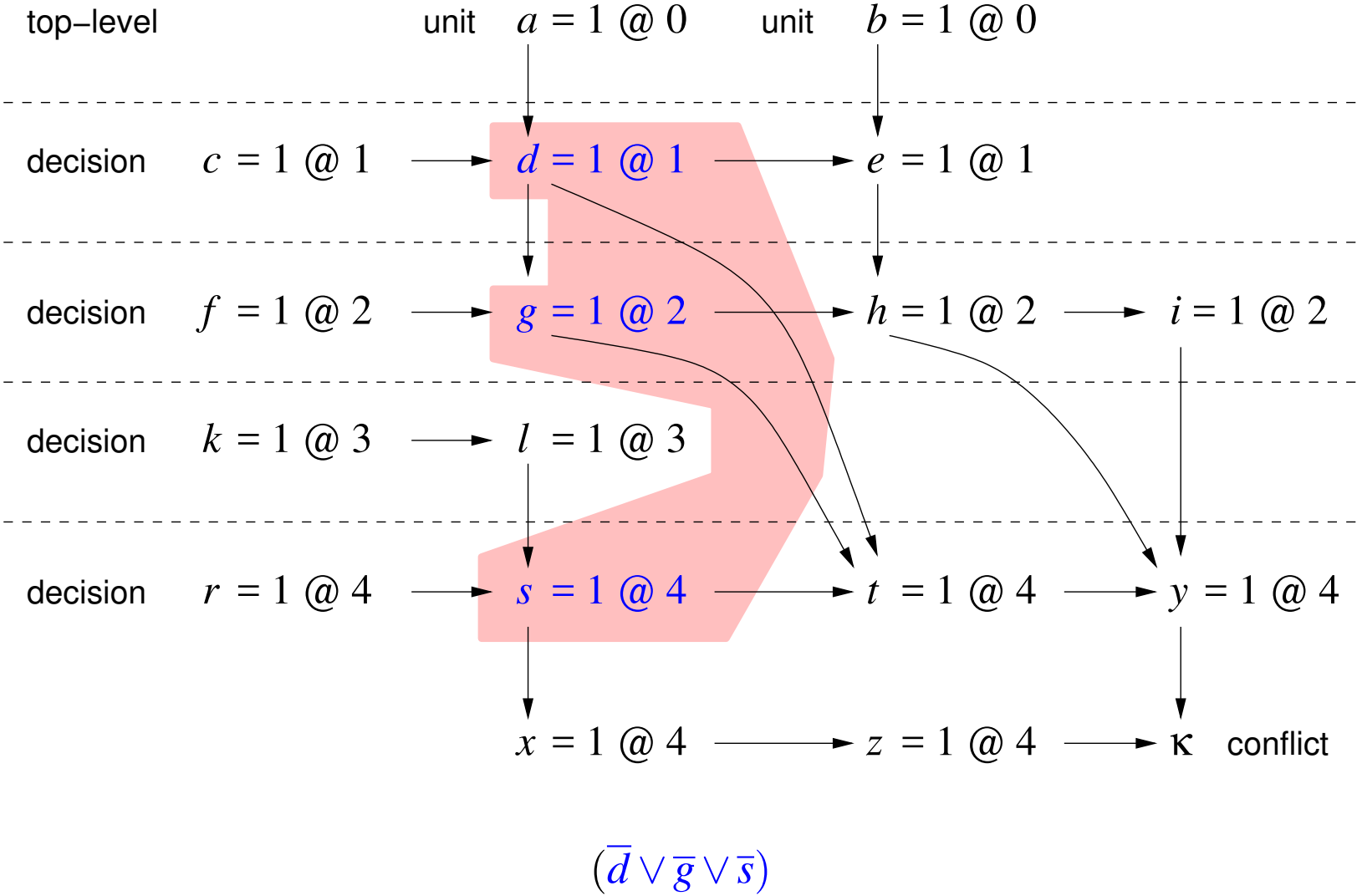
$$(\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h})$$

Recursively Minimizing Learned Clause



$$\begin{array}{c}
 \frac{(b) \quad \frac{\frac{(\bar{d} \vee \bar{b} \vee e) \quad (\bar{e} \vee \bar{d} \vee \bar{g} \vee \bar{s})}{(\bar{b} \vee \bar{d} \vee \bar{g} \vee \bar{s})} \quad \frac{(\bar{e} \vee \bar{g} \vee h) \quad (\bar{d} \vee \bar{g} \vee \bar{s} \vee \bar{h})}{(\bar{e} \vee \bar{d} \vee \bar{g} \vee \bar{s})}}{(\bar{d} \vee \bar{g} \vee \bar{s})}
 \end{array}$$

Recursively Minimized Learned Clause



Decision Heuristics

- number of variable occurrences in (remaining unsatisfied) clauses (LIS)
 - eagerly satisfy many clauses
 - many variations were studied in the 90ies
 - actually expensive to compute
- dynamic heuristics
 - **focus on variables which were usefull recently in deriving learned clauses**
 - can be interpreted as reinforcement learning
 - started with the VSIDS heuristic [MoskewiczMadiganZhaoZhangMalik'01]
 - most solvers rely on the exponential variant in MiniSAT (EVSIDS)
 - recently showed VMTF as effective as VSIDS [Biere-SAT'15] *acts as survey*
- look-ahead
 - spent more time in selecting good variables (and simplification)
 - related to our Cube & Conquer paper [HeuleKullmanWieringaBiere-HVC'11]
 - “The Science of Brute Force” [Heule & Kullman CACM August 2017]

Variable Scoring Schemes

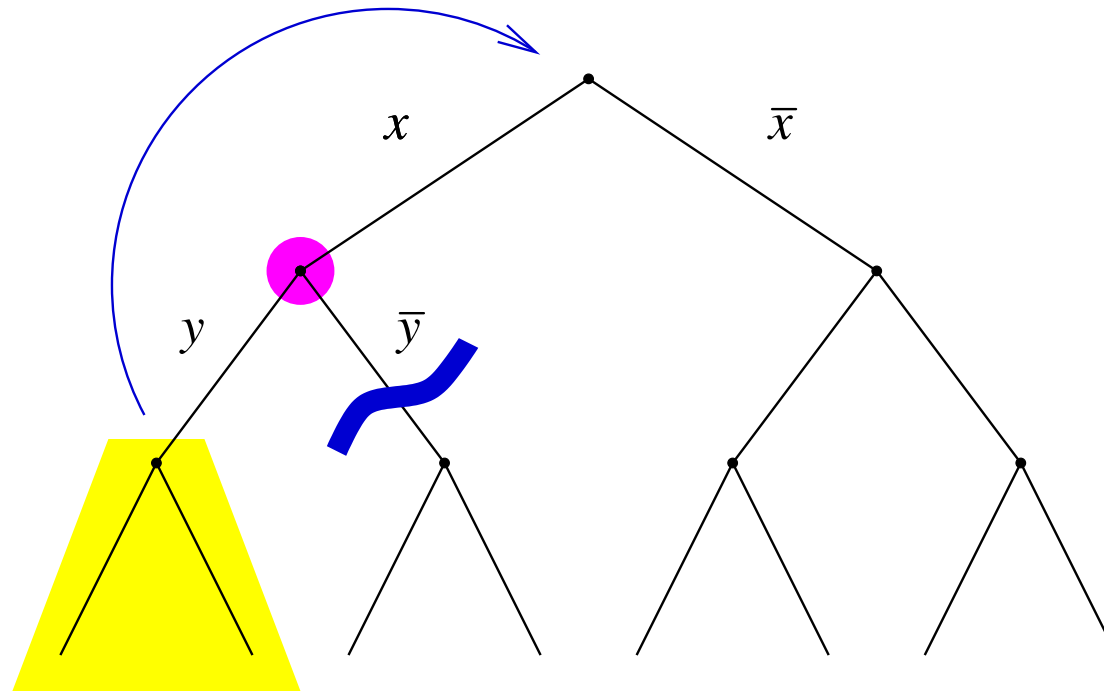
s old score s' new score

	variable score s' after i conflicts		
	bumped	not-bumped	
STATIC	s	s	static decision order
INC	$s + 1$	s	increment scores
SUM	$s + i$	s	sum of conflict-indices
VSIDS	$h_i^{256} \cdot s + 1$	$h_i^{256} \cdot s$	original implementation in Chaff
NVSIDS	$f \cdot s + (1 - f)$	$f \cdot s$	normalized variant of VSIDS
EVSIDS	$s + g^i$	s	exponential MiniSAT dual of NVSIDS
ACIDS	$(s + i)/2$	s	average conflict-index decision scheme
VMTF	i	s	variable move-to-front
VMTF'	b	s	variable move-to-front variant

$0 < f < 1$ $g = 1/f$ $h_i^m = 0.5$ if m divides i $h_i^m = 1$ otherwise

i conflict index b bumped counter

Backjumping



If y has never been used to derive a conflict, then skip \bar{y} case.

Immediately jump back to the \bar{x} case – assuming x was used.

Basic CDCL Loop

```
int basic_cdcl_loop () {  
    int res = 0;  
  
    while (!res)  
        if (unsat) res = 20;  
        else if (!propagate ()) analyze ();    // analyze propagated conflict  
        else if (satisfied ()) res = 10;      // all variables satisfied  
        else decide ();                       // otherwise pick next decision  
  
    return res;  
}
```

Reducing Learned Clauses

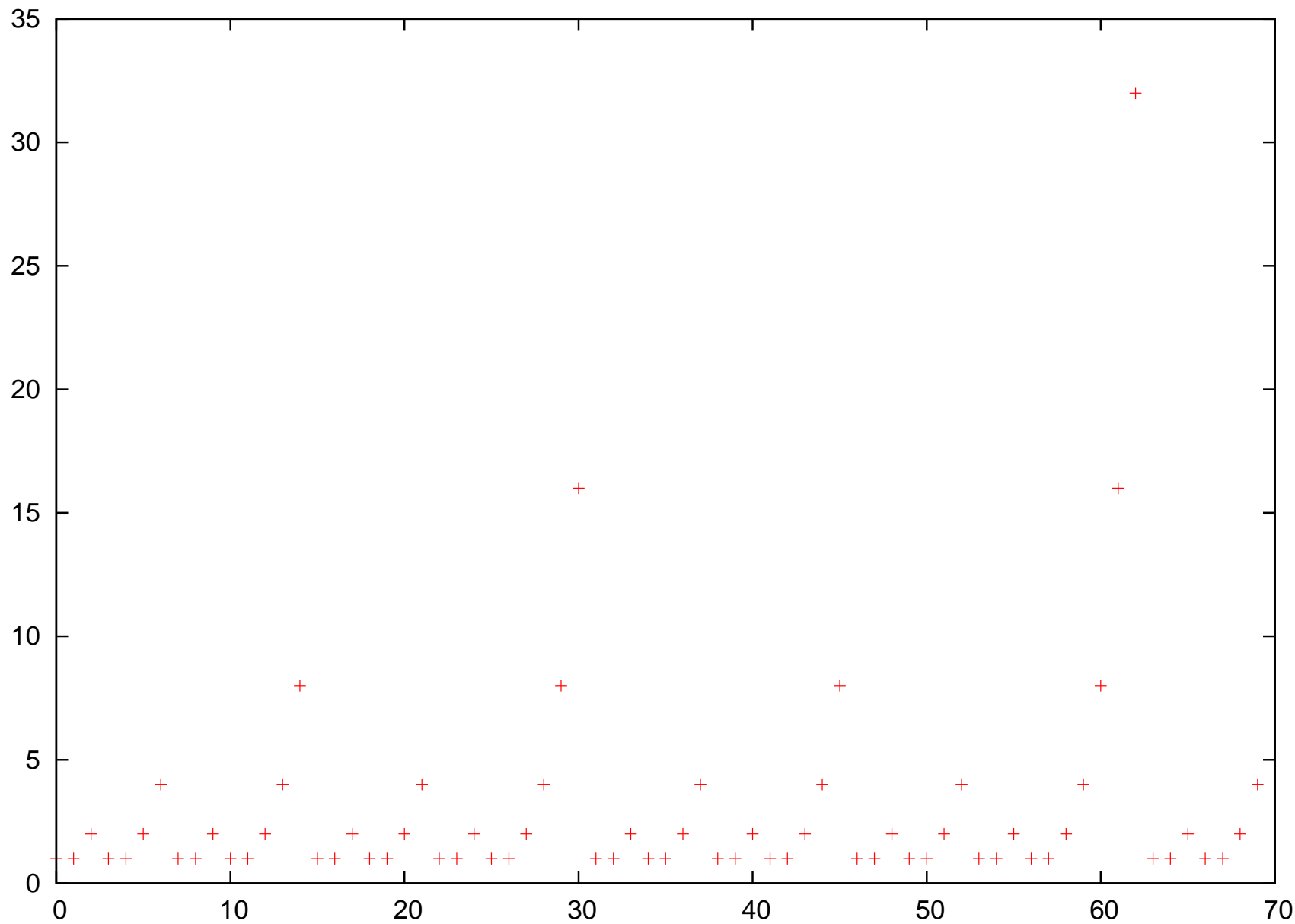
- keeping all learned clauses slows down BCP kind of quadratically
 - so SATO and ReISAT just kept only “short” clauses
- better periodically delete “useless” learned clauses
 - keep a certain number of learned clauses “search cache”
 - if this number is reached MiniSAT reduces (deletes) half of the clauses
 - then maximum number kept learned clauses is increased geometrically
- LBD (glucose level / glue) based prediction for usefulness [AudemardSimon-IJCAI’09]
 - LBD = number of decision-levels in the learned clause
 - allows arithmetic increase of number of kept learned clauses
 - keep clauses with small LBD forever ($\leq 2 \dots 5$)
 - large fixed cache useful for hard satisfiable instances (crypto) [Chanseok Oh]

Restarts

- often it is a good strategy to abandon what you do and restart
 - for satisfiable instances the solver may get stuck in the unsatisfiable part
 - for unsatisfiable instances focusing on one part might miss short proofs
 - restart after the number of conflicts reached a restart limit
- avoid to run into the same dead end
 - by randomization (either on the decision variable or its phase)
 - and/or just keep all the learned clauses
- for completeness dynamically increase restart limit
 - arithmetically, geometrically, Luby, Inner/Outer
- Glucose restarts [AudemardSimon-CP'12]
 - short vs. large window exponential moving average (EMA) over LBD
 - if recent LBD values are larger than long time average then restart

Luby's Restart Intervals

70 restarts in 104448 conflicts



Luby Restart Scheduling

```
unsigned
luby (unsigned i)
{
    unsigned k;

    for (k = 1; k < 32; k++)
        if (i == (1 << k) - 1)
            return 1 << (k - 1);

    for (k = 1;; k++)
        if ((1 << (k - 1)) <= i && i < (1 << k) - 1)
            return luby (i - (1 << (k-1)) + 1);
}

limit = 512 * luby (++restarts);
... // run SAT core loop for 'limit' conflicts
```


Reluctant Doubling Sequence

[Knuth'12]

$$(u_1, v_1) = (1, 1)$$

$$(u_{n+1}, v_{n+1}) = ((u_n \& -u_n == v_n) ? (u_n + 1, 1) : (u_n, 2v_n))$$

$$(1, 1), (2, 1), (2, 2), (3, 1), (4, 1), (4, 2), (4, 4), (5, 1), \dots$$

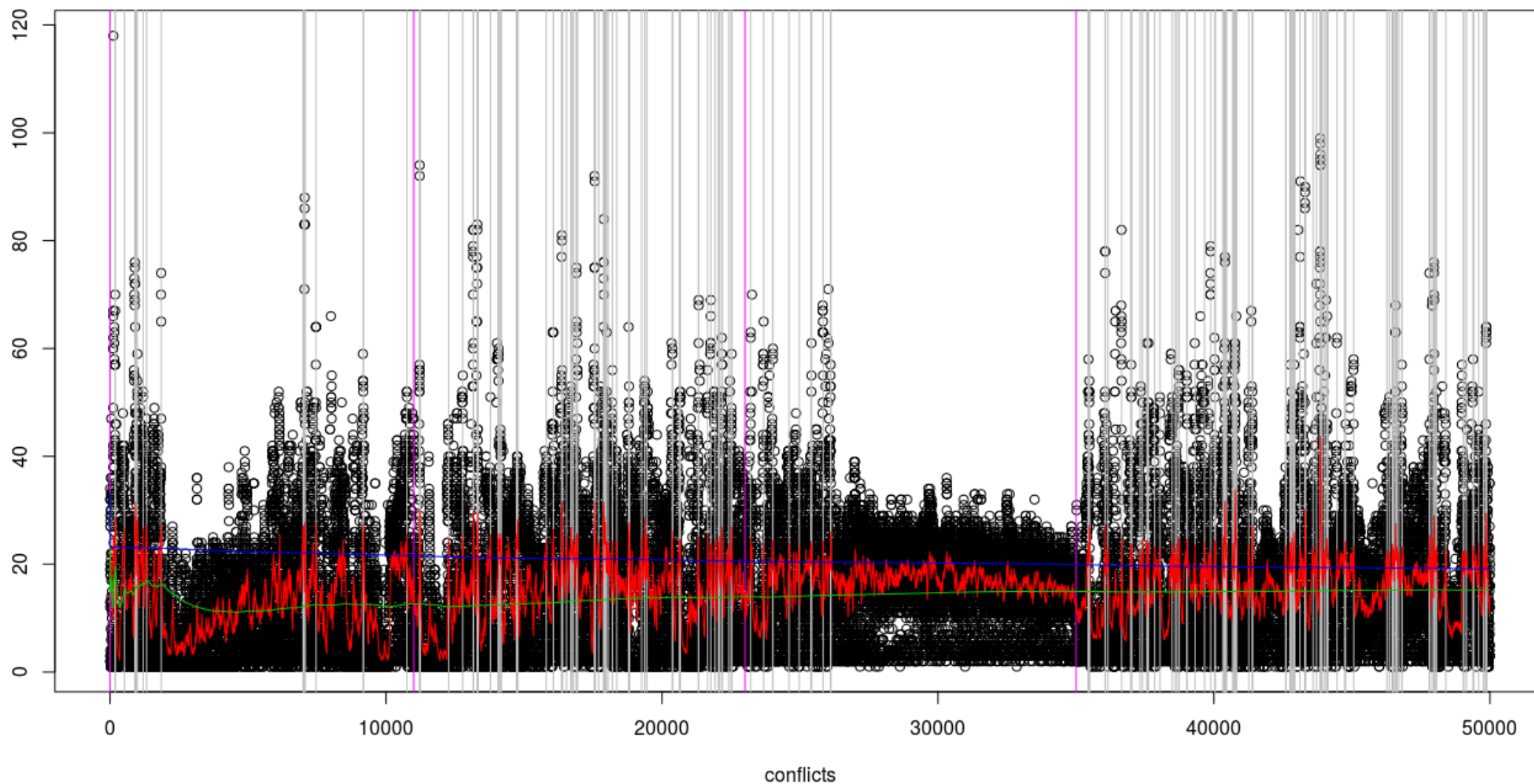
Phase Saving and Rapid Restarts

- phase assignment:
 - assign decision variable to 0 or 1?
 - only thing that matters in satisfiable instances
- “phase saving” as in RSat [PipatsrisawatDarwiche’07]
 - pick phase of last assignment (if not forced to, do not toggle assignment)
 - initially use statically computed phase (typically LIS)
 - so can be seen to maintain a **global full assignment**
 - and thus makes CDCL actually a rather “local” search procedure
- rapid restarts
 - varying restart interval with bursts of restarts
 - not only theoretically avoids local minima
 - works nicely together with phase saving
- reusing the trail can reduce the cost of restarts [RamosVanDerTakHeule-JSAT’11]

Restart Scheduling with Exponential Moving Averages

[BiereFröhlich-POS'15]

- LBD
- | restart
- | inprocessing
- fast *EMA* of LBD with $\alpha = 2^{-5}$
- slow *EMA* of LBD with $\alpha = 2^{-14}$ (ema-14)
- *CMA* of LBD (average)



CDCL Loop with Reduce and Restart

```
int basic_cdcl_loop_with_reduce_and_restart () {  
    int res = 0;  
    while (!res)  
        if (unsat) res = 20;  
        else if (!propagate ()) analyze ();           // analyze propagated conflict  
        else if (satisfied ()) res = 10;             // all variables satisfied  
        else if (restarting ()) restart ();           // restart by backtracking  
        else if (reducing ()) reduce ();              // collect useless learned clauses  
        else decide ();                               // otherwise pick next decision  
    return res;  
}
```

Actual Code from our New SAT Solver CaDiCaL

```
int Internal::search () {
    int res = 0;
    START (search);
    while (!res)
        if (unsat) res = 20;
        else if (!propagate ()) analyze (); // analyze propagated conflict
        else if (iterating) iterate (); // report learned unit
        else if (satisfied ()) res = 10; // all variables satisfied
        else if (terminating ()) break; // limit hit or asynchronous abort
        else if (restarting ()) restart (); // restart by backtracking
        else if (reducing ()) reduce (); // collect useless learned clauses
        else if (probing ()) probe (); // failed literal probing
        else if (subsuming ()) subsume (); // subsumption algorithm
        else if (eliminating ()) elim (); // bounded variable elimination
        else if (compactifying ()) compact (); // collect internal variables
        else decide (); // otherwise pick next decision
    STOP (search);
    return res;
}
```

<https://github.com/arminbiere/cadical>

<https://fmv.jku.at/cadical>

Two-Watched Literal Schemes

- original idea from SATO [ZhangStickel'00]
 - invariant:

always watch two non-false literals
 - if a watched literal becomes false replace it
 - if no replacement can be found clause is either unit or empty
 - original version used head and tail pointers on Tries
- improved variant from Chaff [MoskewiczMadiganZhaoZhangMalik'01]
 - watch pointers can move arbitrarily SATO: head forward, tail backward
 - no update needed during backtracking
- one watch is enough to ensure correctness but looses arc consistency
- reduces visiting clauses by 10x
 - particularly useful for large and many learned clauses
- blocking literals [ChuHarwoodStuckey'09]
- special treatment of short clauses (binary [PilarskiHu'02] or ternary [Ryan'04])
- cache start of search for replacement [Gent-JAIR'13]

Proofs / RUP / DRUP

- original idea for proofs: proof traces / sequence consisting of “learned clauses”
- can be checked clause by clause by unit propagation
- reverse unit implied clauses (RUP) [GoldbergNovikov’03][VanGelder’12]
- deletion information (DRUP): proof trace of added and deleted clauses
- RUP in SAT competition 2007, 2009, 2011, DRUP since 2013 to certify UNSAT

Blocked Clauses

[Kullman-DAM’99] [JärvisaloHeuleBiere-JAR’12]

- clause $\overbrace{(a \vee l)}^C$ “blocked” on l w.r.t. CNF $\overbrace{(\bar{a} \vee b) \wedge (l \vee c) \wedge \underbrace{(\bar{l} \vee \bar{a})}_D}^F$
 - all resolvents of C on l with clauses D in F are tautological
- blocked clauses are “redundant” too
 - adding or removing blocked clauses does not change satisfiability status
 - however it might change the set of models

Resolution Asymmetric Tautologies (RAT)

“Inprocessing Rules” [JärvisaloHeuleBiere-IJCAR’12]

- justify complex preprocessing algorithms in Lingeling
 - examples are adding blocked clauses or variable elimination
 - interleaved with research (forgetting learned clauses = reduce)
- need more general notion of redundancy criteria
 - simply replace “resolvents are tautological” by “resolvents on l are RUP”

$$(a \vee l) \quad \text{RAT on } l \text{ w.r.t.} \quad (\bar{a} \vee b) \wedge (l \vee c) \wedge \underbrace{(\bar{l} \vee b)}_D$$

- deletion information is again essential (DRAT)
- now mandatory in the main track of the last two SAT competitions

Propagation Redundant (PR)

“Short Proofs Without New Variables” [HeuleKieslBiere-CADE’17] *best paper*

- more general than RAT: short proofs for pigeon hole formulas without new variables
- C propagation redundant if \exists (partial) assignment ω satisfying C with $F \mid \bar{C} \vdash_1 F \mid \omega$

Personal SAT Solver History

